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Bulletin No. PAXDP-A
Drawing No. LP0578
Released 4/04

# MODEL PAXDP – 1/8 DIN DUAL PROCESS INPUT METER

- *ACCEPTS TWO 4 - 20 mA OR 0 - 10 VDC INPUT SIGNALS*
- *PROGRAMMABLE A/D CONVERSION RATE, 5 TO 105 READINGS PER SECOND*
- *5-DIGIT 0.56" RED SUNLIGHT READABLE DISPLAY*
- *VARIABLE INTENSITY DISPLAY*
- *LINEARIZATION/SQUARE ROOT EXTRACTION INPUT RANGE*
- *PROGRAMMABLE FUNCTION KEYS/USER INPUTS*
- *9 DIGIT TOTALIZER (INTEGRATOR) WITH BATCHING*
- *OPTIONAL CUSTOM UNITS OVERLAY W/BACKLIGHT*
- *FOUR SETPOINT ALARM OUTPUTS (W/OPTION CARD)*
- *COMMUNICATION AND BUS CAPABILITIES (W/OPTION CARD)*
- *RETRANSMITTED ANALOG OUTPUT (W/OPTION CARD)*
- *NEMA 4X/IP65 SEALED FRONT BEZEL*

## GENERAL DESCRIPTION

The PAXDP Dual Process Input Meter offers many features and performance capabilities to suit a wide range of industrial applications. Available in two models, AC or DC power, the meter has the capability to accept two, 4 to 20 mA or 0 to 10 VDC input signals. Each input signal can be independently scaled and displayed. In addition, a math function can be performed on the two signals, C + A + B, C - A - B, C + A - B, AB / C, CA / B, or C (A / B - 1). Any of the three meter values can have Alarms, Comms, and/or a Retransmitted Analog Output capability by simply adding optional cards. The optional plug-in output cards allow the opportunity to configure the meter for current applications, while providing easy upgrades for future needs.

The update rate of the meter is user selectable. This will help in those applications where a quick response from the meter is of the utmost importance. The rate can be adjusted from eight selections with a minimum of 5 updates/second to a maximum of 105 updates/second.

The meters employ a bright 0.56" (14.2 mm) red sunlight readable LED display. The intensity of display can be adjusted from dark room applications up to sunlight readable, making it ideal for viewing in bright light applications.

The meters provide a MAX and MIN reading memory with programmable capture time. The capture time is used to prevent detection of false max or min readings which may occur during start-up or unusual process events.

The signal totalizer (integrator) can be used to compute a time-input product. This can be used to provide a readout of totalized flow, calculate service intervals of motors or pumps, etc. The totalizer can also accumulate batch operations.

The meter has four setpoint outputs, implemented on Plug-in option cards. The Plug-in cards provide dual FORM-C relays (5A), quad FORM-A (3A), or either quad sinking or quad sourcing open collector logic outputs. The setpoint alarms can be configured to suit a variety of control and alarm requirements.

Communication and Bus Capabilities are also available as option cards. The standard output is in Modbus Protocol. Any of the following option cards, RS232, RS485, DeviceNet, or Profibus can be used with the meter. Readout values and setpoint alarm values can be controlled through the bus. Additionally, the meters have a feature that allows a remote computer to directly control the outputs of the meter.

A linear DC output signal is available as an optional Plug-in card. The card provides either 20 mA or 10 V signals. The output can be scaled independent of the input range and can track either the input, totalizer, max/min readings, or math calculation value.

Once the meters have been initially configured, the parameter list may be locked out from further modification in its entirety or only the setpoint values can be made accessible.

The meters have been specifically designed for harsh industrial environments. With NEMA 4X/IP65 sealed bezel and extensive testing of noise effects to CE requirements, the meter provides a tough yet reliable application solution.

## SAFETY SUMMARY

All safety related regulations, local codes and instructions that appear in this literature or on equipment must be observed to ensure personal safety and to prevent damage to either the instrument or equipment connected to it. If equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

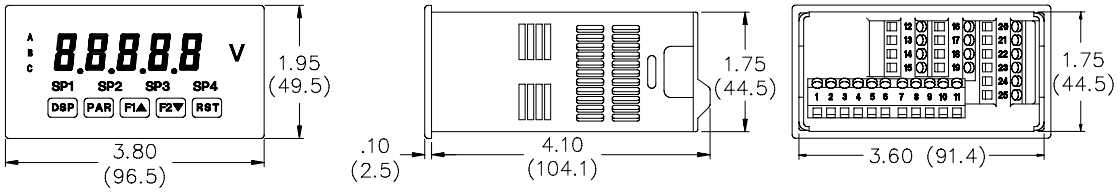
Do not use this unit to directly command motors, valves, or other actuators not equipped with safeguards. To do so can be potentially harmful to persons or equipment in the event of a fault to the unit.

**CAUTION: Read complete instructions prior to installation and operation of the unit.**

**CAUTION: Risk of electric shock.**

## DIMENSIONS In inches (mm)

Note: Recommended minimum clearance (behind the panel) for mounting clip installation is 2.1" (53.4) H x 5.0" (127) W.



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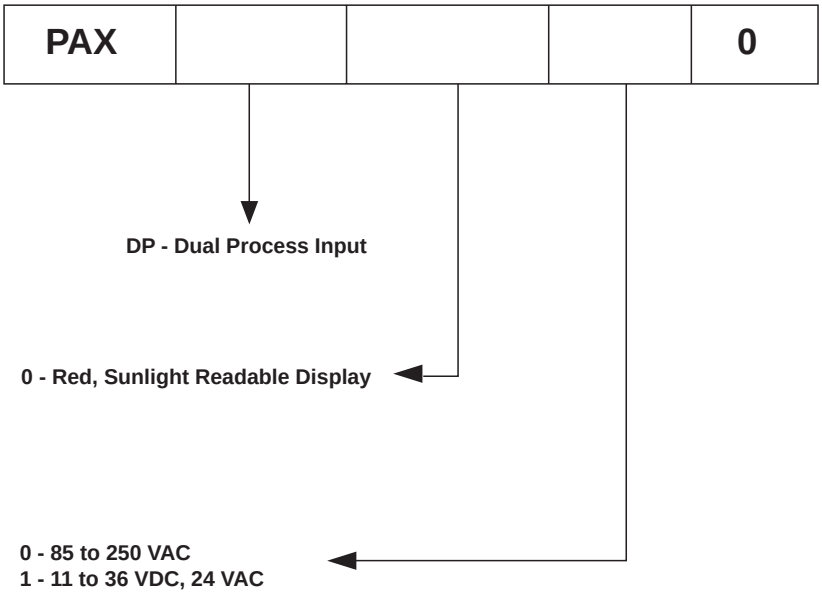
# ORDERING INFORMATION

### Meter Part Numbers




### Option Card and Accessories Part Numbers

| TYPE | MODEL NO. | DESCRIPTION | PART NUMBERS |
|---|---|---|---|
| Optional Plug-In Cards | PAXCDS | Dual Setpoint Relay Output Card | PAXCDS10 |
| | | Quad Setpoint Relay Output Card | PAXCDS20 |
| | | Quad Setpoint Sinking Open Collector Output Card | PAXCDS30 |
| | | Quad Setpoint Sourcing Open Collector Output Card | PAXCDS40 |
| | PAXCDC | RS485 Serial Communications Output Card with Terminal Block | PAXCDC10 |
| | | Extended RS485 Serial Communications Output Card with Dual RJ11 Connector | PAXCDC1C |
| | | RS232 Serial Communications Output Card with Terminal Block | PAXCDC20 |
| | | Extended RS232 Serial Communications Output Card with 9 Pin D Connector | PAXCDC2C |
| | | DeviceNet Communications Card | PAXCDC30 |
| | | Profibus-DP Communications Card | PAXCDC50 |
| | PAXCDL | Analog Output Card | PAXCDL10 |
| Accessories | PAXLBK | Units Label Kit Accessory | PAXLBK10 |

*Note: For Modbus communications use RS485 Communications Output Card and configure communication (tYPE) parameter for Modbus.*

# GENERAL METER SPECIFICATIONS

1. **DISPLAY**: 5 digit, 0.56" (14.2 mm) variable intensity red sunlight readable (-19999 to 99999)
2. **POWER**:
   AC Versions:
   AC Power: 85 to 250 VAC, 50/60 Hz, 21 VA
   Isolation: 2300 Vrms for 1 min. to all inputs and outputs.
   DC Versions: (Derate operating temperature to 40° C if three plug-in option cards or PAXCDC50 are installed.)
   DC Power: 18 to 36 VDC, 13 W
   AC Power: 24 VAC, ± 10%, 50/60 Hz, 16 VA
   Isolation: 500 Vrms for 1 min. to all inputs and outputs (50 V working).
3. **ANNUNCIATORS**:
   A - Programmable Display
   B - Programmable Display
   C - Programmable Display
   SP1 - Setpoint alarm 1 is active
   SP2 - Setpoint alarm 2 is active
   SP3 - Setpoint alarm 3 is active
   SP4 - Setpoint alarm 4 is active
   Units Label - Optional units label backlight
4. **KEYPAD**: 3 programmable function keys, 5 keys total
5. **A/D CONVERTER**: 16 bit resolution
6. **UPDATE RATES**:
   A/D conversion rate: Adjustable 5.3 to 105 readings/sec.
   Step response: (to within 99% of final readout value with digital filter disabled)

| INPUT UPDATE RATE | MAX. TIME (msec) |
|---|---|
| 5.3 | 770 |
| 7.5 | 560 |
| 16.7 | 260 |
| 19.8 | 220 |
| 20 | 220 |
| 30 | 150 |
| 105 | 60 |

   Display update rate: adjustable 1 to 20 readings/sec.
   Setpoint output on/off delay time: 0 to 3275 sec.
   Analog output update rate: 0 to 10 sec
   Max./Min. capture delay time: 0 to 3275 sec.
7. **DISPLAY MESSAGES**:
   "OLOL" - Appears when measurement exceeds + signal range.
   "ULUL" - Appears when measurement exceeds - signal range
   ". . . ." - Appears when display values exceed + display range.
   "- . . ." - Appears when display values exceed - display range.
8. **SENSOR INPUTS**:

| INPUT (RANGE) | ACCURACY* (18 to 28°C) | ACCURACY* (0 to 50°C) | IMPEDANCE/ COMPLIANCE | MAX CONTINUOUS OVERLOAD | DISPLAY RESOLUTION |
|---|---|---|---|---|---|
| ±20 mA (-26 to 26 mA) | 0.03% of reading +2 µA | 0.12% of reading +3 µA | 24.6 ohm | 150 mA | 1 µA |
| ±10 VDC (-13 to 13 VDC) | 0.03% of reading +2 mV | 0.12% of reading +3 mV | 500 Kohm | 50 V | 1 mV |

* After 20 minute warm-up. Accuracy is specified in two ways: Accuracy over an 18 to 28°C and 10 to 75% RH environment; and accuracy over a 0 to 50°C and 0 to 85% RH (non-condensing environment). Accuracy over the 0 to 50°C range includes the temperature coefficient effect of the meter.

9. **EXCITATION POWER**:
   Transmitter Power: 18 VDC, ±20%, unregulated, 70 mA max. per input channel.
10. **LOW FREQUENCY NOISE REJECTION**:
    Normal Mode: (digital filter off)

| INPUT UPDATE RATE | 50 Hz ±1 Hz | 60 Hz ±1 Hz |
|---|---|---|
| 5.3 | >90 dB | >65 dB |
| 7.5 | >60 dB | >55 dB |
| 16.7 | >100 dB | >50 dB |
| 19.8* | >60 dB | >95 dB |
| 20 | >55 dB | >100 dB |
| 30 | >20 dB | >20 dB |
| 105 | >20 dB | >13 dB |

    *Note: 19.8 Hz Input Rate provides best rate performance and simultaneous 50/60 Hz rejection.
    Common Mode: >100 dB @ 50/60 ±1 Hz (19.8 or 20 Input Rate)
11. **USER INPUTS**: Three programmable user inputs
    Max. Continuous Input: 30 VDC
    Isolation To Sensor Input A Common: 500 Vrms for 1 min;
    Working Voltage: 50 V
    Isolation To Sensor Input B Common: Not isolated.

| INPUT STATE | SINKING INPUTS 22 KΩ pull-up to +5 V | SOURCING INPUTS 22 KΩ pull-down |
|---|---|---|
| Active | $V_{IN}$ < 0.9 VDC | $V_{IN}$ > 3.6 VDC |
| Inactive | $V_{IN}$ > 3.6 VDC | $V_{IN}$ < 0.9 VDC |

    Response Time: 20 msec. max.
    Logic State: Jumper selectable for sink/source logic
12. **TOTALIZER**:
    Function:
    Time Base: second, minute, hour, or day
    Batch: Can accumulate (gate) input display from a user input
    Time Accuracy: 0.01% typical
    Decimal Point: 0 to 0.0000
    Scale Factor: 0.001 to 65.000
    Low Signal Cut-out: -19,999 to 99,999
    Total: 9 digits, display alternates between high order and low order readouts
13. **CUSTOM LINEARIZATION**:
    Data Point Pairs: Selectable from 2 to 16
    Display Range: -19,999 to 99,999
    Decimal Point: 0 to 0.0000
14. **MEMORY**: Nonvolatile memory retains all programmable parameters and display values.
15. **ENVIRONMENTAL CONDITIONS**:
    Operating Temperature Range: 0 to 50°C (0 to 45°C with all three plug-in option cards installed)
    Storage Temperature Range: -40 to 60°C
    Operating and Storage Humidity: 0 to 85% max. RH non-condensing
    Altitude: Up to 2000 meters

16. **CERTIFICATIONS AND COMPLIANCES**:

**SAFETY**

Type 4X Enclosure rating (Face only), UL50

IEC 1010-1, EN 61010-1: Safety requirements for electrical equipment for measurement, control, and laboratory use, Part I

IP65 Enclosure rating (Face only), IEC 529

IP20 Enclosure rating (Rear of unit), IEC 529

**ELECTROMAGNETIC COMPATIBILITY**

Emissions and Immunity to EN 61326: Electrical Equipment for Measurement, Control and Laboratory use.

**Immunity to Industrial Locations:**

| | | |
|---|---|---|
| Electrostatic discharge | EN 61000-4-2 | Criterion A<br>4 kV contact discharge<br>8 kV air discharge |
| Electromagnetic RF fields | EN 61000-4-3 | Criterion A<br>10 V/m |
| Fast transients (burst) | EN 61000-4-4 | Criterion A<br>2 kV power<br>1 kV signal |
| Surge | EN 61000-4-5 | Criterion A<br>1 kV L-L,<br>2 kV L&N-E power |
| Voltage dip/interruptions | EN 61000-4-11 | Criterion A<br>0.5 cycle |
| RF conducted interference | EN 61000-4-6 | Criterion A<br>3 V/rms |

**Emissions:**

| | | |
|---|---|---|
| AC powered | EN 55011 | Class B |
| DC powered | EN 55011 | Class A |

*Notes:*

*1. Criterion A: Normal operation within specified limits.*

*2. Criterion B: Temporary loss of performance from which the unit self-recovers.*

*Refer to EMC Installation Guidelines section of the bulletin for additional information.*

17. **CONNECTIONS**: High compression cage-clamp terminal block
Wire Strip Length: 0.3" (7.5 mm)
Wire Gage: 30-14 AWG copper wire
Torque: 4.5 inch-lbs (0.51 N-m) max.

18. **CONSTRUCTION**: This unit is rated for NEMA 4X/IP65 outdoor use. IP20 Touch safe. Installation Category II, Pollution Degree 2. One piece bezel/case. Flame resistant. Synthetic rubber keypad. Panel gasket and mounting clip included.

19. **WEIGHT**: 10.4 oz. (295 g)

# ACCESSORIES

## UNITS LABEL KIT (PAXLBK)

Each meter has a units indicator with backlighting that can be customized using the Units Label Kit. The backlight is controlled in the programming.

# OPTIONAL PLUG-IN OUTPUT CARDS

**WARNING: Disconnect all power to the unit before installing Plug-in cards.**

## Adding Option Cards

The PAX and MPAX series meters can be fitted with up to three optional plug-in cards. The details for each plug-in card can be reviewed in the specification section below. Only one card from each function type can be installed at one time. The function types include Setpoint Alarms (PAXCDS), Communications (PAXCDC), and Analog Output (PAXCDL). The plug-in cards can be installed initially or at a later date.

## COMMUNICATION CARDS (PAXCDC)

A variety of communication protocols are available for the PAX and MPAX series. Only one of these cards can be installed at a time. *Note: For Modbus communications use RS485 Communications Output Card and configure communication (tYPE) parameter for Modbus.*

PAXCDC10 - RS485 Serial (Terminal Block)
PAXCDC1C - RS485 Serial (Dual RJ11 Connector)
PAXCDC20 - RS232 Serial (Terminal Block)
PAXCDC2C - RS232 Serial (9 Pin D Connector)
PAXCDC30 - DeviceNet
PAXCDC50 - Profibus-DP

**SERIAL COMMUNICATIONS CARD**

**Type**: RS485 or RS232
**Isolation To Sensor & User Input Commons**: 500 Vrms for 1 min.
Working Voltage: 50 V. Not Isolated from all other commons.
**Baud**: 300 to 38,400
**Data**: 7/8 bits
**Parity**: no, odd or even
**Bus Address**: Selectable 0 to 99, (RLC Protocol) or 1 to 247 (Modbus Protocol), Max. 32 meters per line (RS485)
**Transmit Delay**: Selectable for 0 to 0.250 sec (+2 msec min)

**DEVICENET™ CARD**

**Compatibility**: Group 2 Server Only, not UCMM capable
**Baud Rates**: 125 Kbaud, 250 Kbaud, and 500 Kbaud
**Bus Interface**: Phillips 82C250 or equivalent with MIS wiring protection per DeviceNet™ Volume I Section 10.2.2.
**Node Isolation**: Bus powered, isolated node
**Host Isolation**: 500 Vrms for 1 minute (50 V working) between DeviceNet™ and meter input common.

**PROFIBUS-DP CARD**

**Fieldbus Type:** Profibus-DP as per EN 50170, implemented with Siemens SPC3 ASIC
**Conformance:** PNO Certified Profibus-DP Slave Device
**Baud Rates:** Automatic baud rate detection in the range 9.6 Kbaud to 12 Mbaud
**Station Address:** 0 to 126, set by the master over the network. Address stored in non-volatile memory.
**Connection:** 9-pin Female D-Sub connector
**Network Isolation:** 500 Vrms for 1 minute (50 V working) between Profibus network and sensor and user input commons. Not isolated from all other commons.

## SETPOINT CARDS (PAXCDS)

The PAX and MPAX series has 4 available setpoint alarm output plug-in cards. Only one of these cards can be installed at a time. (Logic state of the outputs can be reversed in the programming.) These plug-in cards include:

PAXCDS10 - Dual Relay, FORM-C, Normally open & closed
PAXCDS20 - Quad Relay, FORM-A, Normally open only
PAXCDS30 - Isolated quad sinking NPN open collector
PAXCDS40 - Isolated quad sourcing PNP open collector

**DUAL RELAY CARD**

**Type**: Two FORM-C relays
**Isolation To Sensor & User Input Commons**: 2000 Vrms for 1 min.
Working Voltage: 240 Vrms
**Contact Rating**:
One Relay Energized: 5 amps @ 120/240 VAC or 28 VDC (resistive load), 1/8 HP @120 VAC, inductive load
Total current with both relays energized not to exceed 5 amps
**Life Expectancy**: 100 K cycles min. at full load rating. External RC snubber extends relay life for operation with inductive loads

**QUAD RELAY CARD**

**Type**: Four FORM-A relays
**Isolation To Sensor & User Input Commons**: 2300 Vrms for 1 min.
Working Voltage: 250 Vrms
**Contact Rating**:
One Relay Energized: 3 amps @ 240 VAC or 30 VDC (resistive load), 1/10 HP @120 VAC, inductive load
Total current with all four relays energized not to exceed 4 amps
**Life Expectancy**: 100 K cycles min. at full load rating. External RC snubber extends relay life for operation with inductive loads

**QUAD SINKING OPEN COLLECTOR CARD**

**Type**: Four isolated sinking NPN transistors.
**Isolation To Sensor & User Input Commons**: 500 Vrms for 1 min.
Working Voltage: 50 V. Not Isolated from all other commons.
**Rating**: 100 mA max @ $V_{SAT}$ = 0.7 V max. $V_{MAX}$ = 30 V

**QUAD SOURCING OPEN COLLECTOR CARD**

**Type**: Four isolated sourcing PNP transistors.
**Isolation To Sensor & User Input Commons**: 500 Vrms for 1 min.
Working Voltage: 50 V. Not Isolated from all other commons.
**Rating**: Internal supply: 24 VDC ± 10%, 30 mA max. total
External supply: 30 VDC max., 100 mA max. each output

**ALL FOUR SETPOINT CARDS**

**Response Time**: See update rates step response specification; add 6 msec (typical) for relay card

## LINEAR DC OUTPUT (PAXCDL)

Either a 0(4)-20 mA or 0-10 V retransmitted linear DC output is available from the analog output plug-in card. The programmable output low and high scaling can be based on various display values. Reverse slope output is possible by reversing the scaling point positions.

PAXCDL10 - Retransmitted Analog Output Card

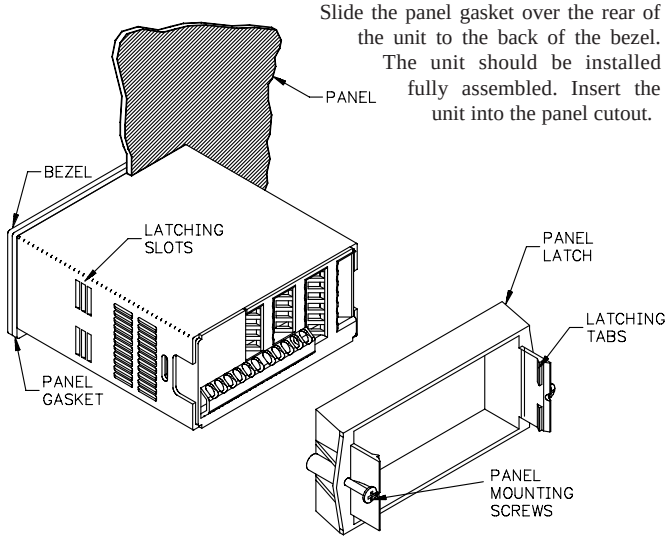
**ANALOG OUTPUT CARD**

**Types**: 0 to 20 mA, 4 to 20 mA or 0 to 10 VDC
**Isolation To Sensor & User Input Commons**: 500 Vrms for 1 min.
Working Voltage: 50 V. Not Isolated from all other commons.
**Accuracy**: 0.17% of FS (18 to 28°C); 0.4% of FS (0 to 50°C)
**Resolution**: 1/3500
**Compliance**: 10 VDC: 10 KΩ load min., 20 mA: 500 Ω load max.
**Update time**: See update rates step response specification

# 1.0 Installing the Meter

### *Installation*

The PAX meets NEMA 4X/IP65 requirements for indoor use when properly installed. The unit is intended to be mounted into an enclosed panel. Prepare the panel cutout to the dimensions shown. Remove the panel latch from the unit. Slide the panel gasket over the rear of the unit to the back of the bezel. The unit should be installed fully assembled. Insert the unit into the panel cutout.




While holding the unit in place, push the panel latch over the rear of the unit so that the tabs of the panel latch engage in the slots on the case. The panel latch should be engaged in the farthest forward slot possible. To achieve a proper seal, tighten the latch screws evenly until the unit is snug in the panel (Torque to approximately 7 in-lbs [79N-cm]). Do not over-tighten the screws.

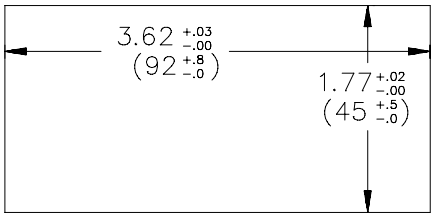
### *Installation Environment*

The unit should be installed in a location that does not exceed the maximum operating temperature and provides good air circulation. Placing the unit near devices that generate excessive heat should be avoided.

The bezel should be cleaned only with a soft cloth and neutral soap product. Do NOT use solvents. Continuous exposure to direct sunlight may accelerate the aging process of the bezel.

Do not use tools of any kind (screwdrivers, pens, pencils, etc.) to operate the keypad of the unit.

PANEL CUT-OUT




# 2.0 Setting the Jumpers

The meter has three jumpers that must be checked and/or changed prior to applying power. The following Jumper Selection Figures show an enlargement of the jumper area.

To access the jumpers, remove the meter base from the case by firmly squeezing and pulling back on the side rear finger tabs. This should lower the latch below the case slot (which is located just in front of the finger tabs). It is recommended to release the latch on one side, then start the other side latch.

### Input Jumpers

These jumpers are used to select the proper input types, Voltage (V) or Current (I). The input type selected in programming must match the jumper setting. See the Jumper Selection Figures for more details.

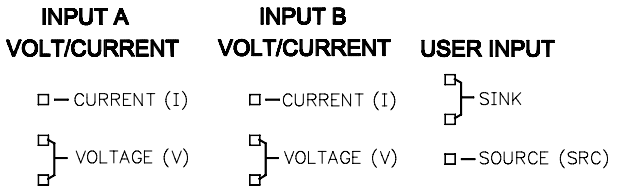
### User Input Logic Jumper

This jumper selects the logic state of all the user inputs. If the user inputs are not used, it is not necessary to check or move this jumper.

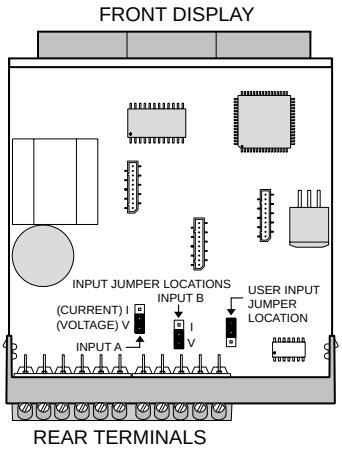
## PAXDP Jumper Selection

JUMPER SELECTIONS

The ⌒ indicates factory setting.




Note: In the figures above, the text shown in parenthesis is printed on the circuit board to help with proper jumper positioning.



# 3.0 WIRING THE METER

## WIRING OVERVIEW

Electrical connections are made via screw-clamp terminals located on the back of the meter. All conductors should conform to the meter's voltage and current ratings. All cabling should conform to appropriate standards of good installation, local codes and regulations. It is recommended that power supplied to the meter (DC or AC) be protected by a fuse or circuit breaker.

When wiring the meter, compare the numbers embossed on the back of the meter case against those shown in wiring drawings for proper wire position. Strip the wire, leaving approximately 0.3" (7.5 mm) bare lead exposed (stranded wires should be tinned with solder). Insert the lead under the correct screw-clamp terminal and tighten until the wire is secure. (Pull wire to verify tightness.) Each terminal can accept up to one #14 AWG (2.55 mm) wire, two #18 AWG (1.02 mm), or four #20 AWG (0.61 mm).

## EMC INSTALLATION GUIDELINES

Although this meter is designed with a high degree of immunity to Electro-Magnetic Interference (EMI), proper installation and wiring methods must be followed to ensure compatibility in each application. The type of the electrical noise, its source or the method of coupling into the unit may be different for various installations. Listed below are some EMC guidelines for successful installation in an industrial environment.

1. The meter should be mounted in a metal enclosure, which is properly connected to protective earth.
2. With use of the lower input ranges or signal sources with high source impedance, the use of shielded cable may be necessary. This helps to guard against stray AC pick-up. Attach the shield to the input common of the meter.
3. To minimize potential noise problems, power the meter from the same power branch, or at least the same phase voltage as that of the signal source.
4. Never run Signal or Control cables in the same conduit or raceway with AC power lines, conductors feeding motors, solenoids, SCR controls, and heaters, etc. The cables should be run in metal conduit that is properly grounded. This is especially useful in applications where cable runs are long and portable two-way radios are used in close proximity or if the installation is near a commercial radio transmitter.
5. Signal or Control cables within an enclosure should be routed as far away as possible from contactors, control relays, transformers, and other noisy components.
6. In extremely high EMI environments, the use of external EMI suppression devices, such as ferrite suppression cores, is effective. Install them on Signal and Control cables as close to the unit as possible. Loop the cable through the core several times or use multiple cores on each cable for additional protection. Install line filters on the power input cable to the unit to suppress power line interference. Install them near the power entry point of the enclosure. The following EMI suppression devices (or equivalent) are recommended:
   Ferrite Suppression Cores for signal and control cables:
   Fair-Rite # 0443167251 (RLC #FCOR0000)
   TDK # ZCAT3035-1330A
   Steward #28B2029-0A0
   Line Filters for input power cables:
   Schaffner # FN610-1/07 (RLC #LFIL0000)
   Schaffner # FN670-1.8/07
   Corcom #1VR3
   *Note: Reference manufacturer's instructions when installing a line filter.*
7. Long cable runs are more susceptible to EMI pickup than short cable runs. Therefore, keep cable runs as short as possible.
8. Switching of inductive loads produces high EMI. Use of snubbers across inductive loads suppresses EMI.
   Snubber: RLC#SNUB0000.

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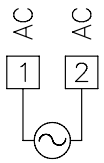
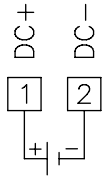
## 3.1 POWER WIRING

**AC Power**
Terminal 1: VAC
Terminal 2: VAC




**DC Power**
Terminal 1: +VDC
Terminal 2: -VDC

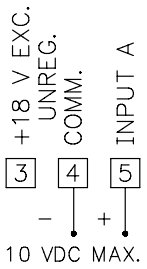


# 3.2 INPUT SIGNAL WIRING

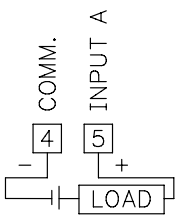
Before connecting signal wires, the Input Range Jumper must be verified for proper position.

## INPUT A SIGNAL WIRING

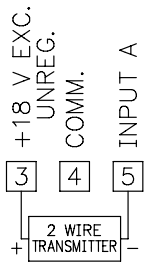
**Voltage Signal (self powered)**
Terminal 4: -VDC
Terminal 5: +VDC



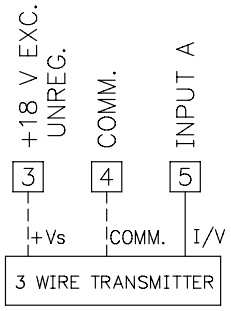

**Current Signal (self powered)**
Terminal 4: -ADC
Terminal 5: +ADC




**Current Signal (2 wire requiring excitation)**
Terminal 3: +ADC
Terminal 5: -ADC

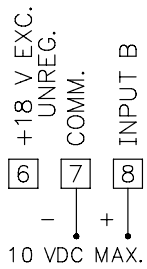



**Voltage/Current Signal (3 wire requiring excitation)**
Terminal 3: +Volt supply
Terminal 4: -ADC (common)
Terminal 5: +ADC (signal)

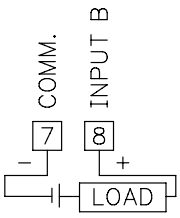



## INPUT B SIGNAL WIRING

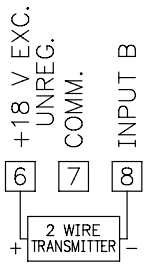
**Voltage Signal (self powered)**
Terminal 6: +VDC
Terminal 8: -VDC



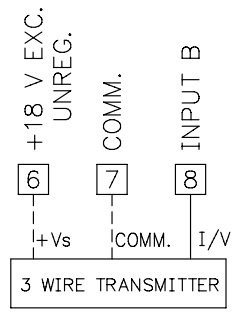

**Current Signal (self powered)**
Terminal 7: -ADC
Terminal 8: +ADC




**Current Signal (2 wire requiring excitation)**
Terminal 6: +ADC
Terminal 8: -ADC




**Voltage/Current Signal (3 wire requiring excitation)**
Terminal 6: +Volt supply
Terminal 7: -ADC (common)
Terminal 8: +ADC (signal)




***CAUTION:*** *Sensor Input B common is NOT isolated from user input common. In order to preserve the safety of the meter application, the sensor input common must be suitably isolated from hazardous live earth referenced voltages; or input common must be at protective earth ground potential. If not, hazardous live voltage may be present at the User Inputs and User Input Common terminals. Appropriate considerations must then be given to the potential of the user input common with respect to earth common; and the common of the isolated plug-in cards with respect to input common.*

---

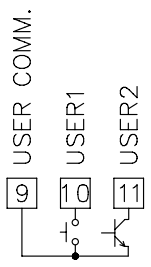
# 3.3 USER INPUT WIRING

Before connecting the wires, the User Input Logic Jumper should be verified for proper position. If not using User Inputs, then skip this section. Only the appropriate User Input terminal has to be wired.

### Sinking Logic

Terminal 9:
Terminal 10-11: } Connect external switching device between appropriate User Input terminal and User Comm.

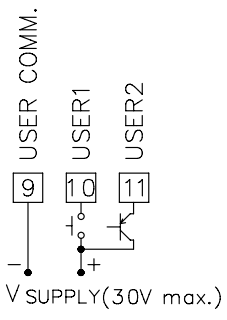
In this logic, the user inputs of the meter are internally pulled up to +5 V with 22 K resistance. The input is active when it is pulled low (<0 .9 V).




### Sourcing Logic

Terminal 9: -VDC thru external switching device
Terminal 10-11: + VDC thru external switching device

In this logic, the user inputs of the meter are internally pulled down to 0 V with 22 K resistance. The input is active when a voltage greater than 3.6 VDC is applied.

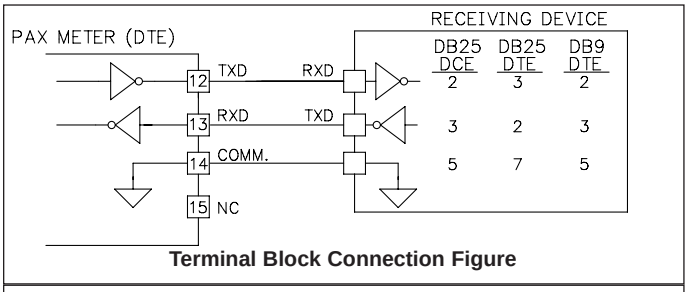


## 3.4 SETPOINT (ALARMS) WIRING
## 3.5 ANALOG OUTPUT WIRING

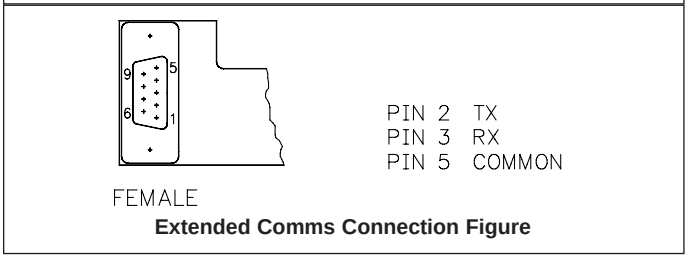
} *See appropriate plug-in card bulletin for details.*

## 3.6 SERIAL COMMUNICATION WIRING

### RS232 Communications




**Terminal Block Connection Figure**




**Extended Comms Connection Figure**

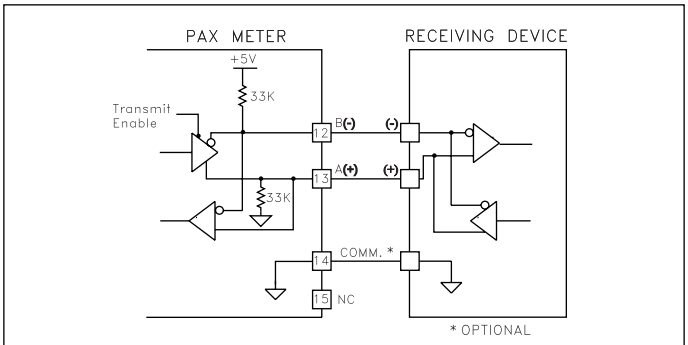
RS232 is intended to allow two devices to communicate over distances up to 50 feet. Data Terminal Equipment (DTE) transmits data on the Transmitted Data (TXD) line and receives data on the Received Data (RXD) line. Data Computer Equipment (DCE) receives data on the TXD line and transmits data on the RXD line. The PAX emulates a DTE. If the other device connected to the meter also emulates a DTE, the TXD and RXD lines must be interchanged for communications to take place. This is known as a null modem connection. Most printers emulate a DCE device while most computers emulate a DTE device.

Some devices cannot accept more than two or three characters in succession without a pause in between. In these cases, the meter employs a busy function.

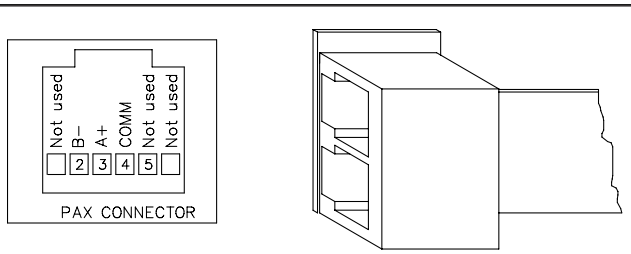
As the meter begins to transmit data, the RXD line (RS232) is monitored to determine if the receiving device is “busy”. The receiving device asserts that it is busy by setting the RXD line to a space condition (logic 0). The meter then suspends transmission until the RXD line is released by the receiving device.

### RS485 Communications

The RS485 communication standard allows the connection of up to 32 devices on a single pair of wires, distances up to 4,000 ft. and data rates as high as 10M baud (the PAX is limited to 19.2k baud). The same pair of wires is used to both transmit and receive data. RS485 is therefore always half-duplex, that is, data cannot be received and transmitted simultaneously.

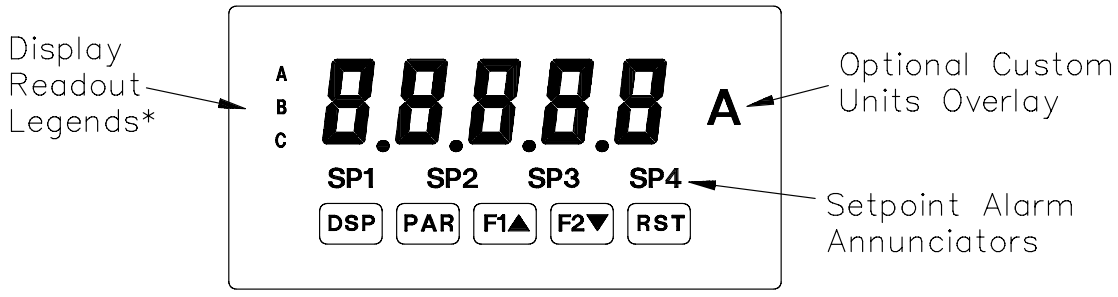



**Terminal Block Connection Figure**




**Extended Comms Connection Figure**

# 4.0 REVIEWING THE FRONT BUTTONS AND DISPLAY




| KEY | DISPLAY MODE OPERATION | PROGRAMMING MODE OPERATION |
|---|---|---|
| **DSP** | Index display through main displays as programmed in 3-LOC | Quit programming and return to display mode |
| **PAR** | Access parameter list | Store selected parameter and index to next parameter |
| **F1▲** | Function key 1; hold for 3 seconds for Second Function 1** | Increment selected parameter value |
| **F2▼** | Function key 2; hold for 3 seconds for Second Function 2** | Decrement selected parameter value |
| **RST** | Reset (Function key)** | Hold with F1▲, F2▼ to scroll value by x1000 |

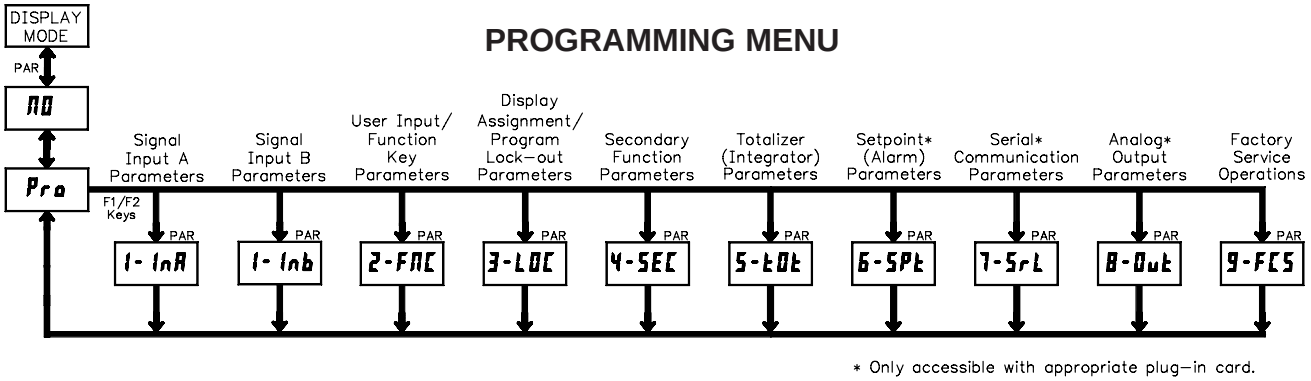
* Display Readout Legends may be locked out in Factory Settings.

** Factory setting for the F1, F2, and RST keys is NO mode.

# 5.0 PROGRAMMING THE METER

## *OVERVIEW*

### PROGRAMMING MENU




### DISPLAY MODE

The meter normally operates in the Display Mode. In this mode, the meter displays can be viewed consecutively by pressing the **DSP** key. The annunciators to the left of the display indicate which display is currently shown; A, B, or C. Each of these displays are programmable and can be locked from view through programming. (See Module 3.)

### PROGRAMMING MODE

Two programming modes are available.

**Full Programming Mode** permits all parameters to be viewed and modified. Upon entering this mode, the front panel keys change to Programming Mode operations. This mode should not be entered while a process is running, since the meter functions and User Input response may not operate properly while in Full Programming Mode.

**Quick Programming Mode** permits only certain parameters to be viewed and/or modified. When viewing parameters (SP1, etc), the front panel keys change to Programming Mode operations, and all meter functions continue to operate properly. Quick Programming Mode is configured in Module 3. The Display Intensity Level "d-LEv" parameter is available in the Quick Programming Mode only when the security code is non-zero. For a description, see Module 9—Factory Service Operations. Throughout this document, Programming Mode (without Quick in front) always refers to "Full" Programming Mode.

### PROGRAMMING TIPS

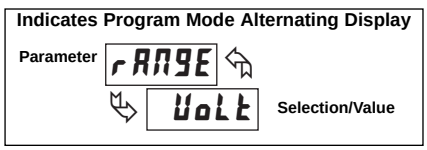
The Programming Menu is organized into ten modules (see above). These modules group together parameters that are related in function. It is recommended to begin programming with Module 1 and proceed through each module in sequence. Note that Modules 6 through 8 are only accessible when the appropriate plug-in option card is installed. If lost or confused while programming, press the **DSP** key to exit programming mode and start over. When programming is complete, it is recommended to record the meter settings on the Parameter Value Chart and lock-out parameter programming with a User Input or lock-out code. (See Modules 2 and 3 for lock-out details.)

### FACTORY SETTINGS

Factory Settings may be completely restored in Module 9. This is a good starting point if encountering programming problems. Throughout the module description sections which follow, the factory setting for each parameter is shown below the parameter display. In addition, all factory settings are listed on the Parameter Value Chart following the programming section.

### ALTERNATING SELECTION DISPLAY

In the module description sections which follow, the dual display with arrows appears for each programming parameter. This is used to illustrate the display alternating between the parameter (top display) and the parameter's Factory Setting (bottom display). In most cases, selections or value ranges for the parameter will be listed on the right.




## *STEP BY STEP PROGRAMMING INSTRUCTIONS:*

### PROGRAMMING MODE ENTRY (PAR KEY)

The Programming Mode is entered by pressing the **PAR** key. If this mode is not accessible, then meter programming is locked by either a security code or a hardware lock. (See Modules 2 and 3 for programming lock-out details.)

### MODULE ENTRY (ARROW & PAR KEYS)

Upon entering the Programming Mode, the display alternates between Pro and the present module (initially no). The arrow keys (**F1▲** and **F2▼**) are used to select the desired module, which is then entered by pressing the **PAR** key.

### PARAMETER (MODULE) MENU (PAR KEY)

Each module has a separate parameter menu. These menus are shown at the start of each module description section which follows. The **PAR** key is pressed to advance to a particular parameter to be changed, without changing the programming of preceding parameters. After completing a module, the display will return to Pro no. From this point, programming may continue by selecting and entering additional modules. (See **MODULE ENTRY** above.)

### PARAMETER SELECTION ENTRY (ARROW & PAR KEYS)

For each parameter, the display alternates between the parameter and the present selection or value for that parameter. For parameters which have a list of selections, the arrow keys (**F1▲** and **F2▼**) are used to sequence through the list until the desired selection is displayed. Pressing the **PAR** key stores and activates the displayed selection, and also advances the meter to the next parameter.

### NUMERICAL VALUE ENTRY (ARROW, RST & PAR KEYS)

For parameters which require a numerical value entry, the arrow keys can be used to increment or decrement the display to the desired value. When an arrow key is pressed and held, the display automatically scrolls up or scrolls down. The longer the key is held, the faster the display scrolls.

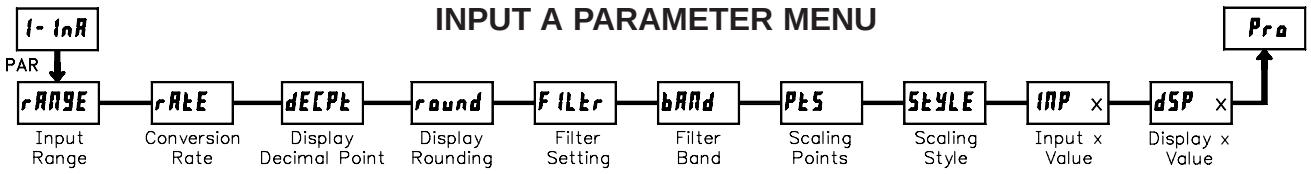
The **RST** key can be used in combination with the arrow keys to enter large numerical values. When the **RST** key is pressed along with an arrow key, the display scrolls by 1000's. Pressing the **PAR** key stores and activates the displayed value, and also advances the meter to the next parameter.

### PROGRAMMING MODE EXIT (DSP KEY or PAR KEY at Pro no)

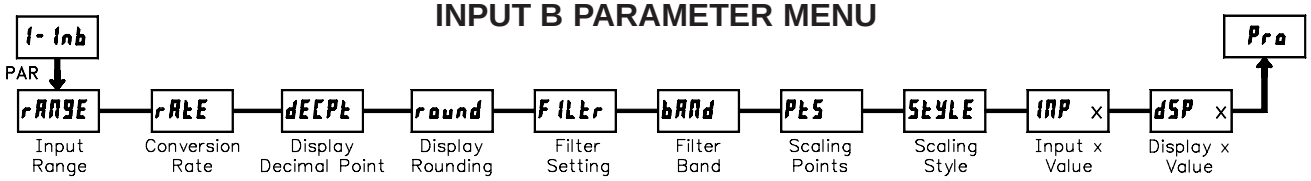
The Programming Mode is exited by pressing the **DSP** key (from anywhere in the Programming Mode) or the **PAR** key (with Pro no displayed). This will commit any stored parameter changes to memory and return the meter to the Display Mode. If a parameter was just changed, the **PAR** key should be pressed to store the change before pressing the **DSP** key. (If power loss occurs before returning to the Display Mode, verify recent parameter changes.)

# 5.1 MODULE 1 - SIGNAL INPUT PARAMETERS

## INPUT A PARAMETER MENU




## INPUT B PARAMETER MENU




### INPUT RANGE

rANGE → UoLt

| SELECTION | RANGE RESOLUTION |
|---|---|
| UoLt | 10.000 V |
| curr | 20.000 mA |
| U-Sqr | ±10.000 V - Square Root Extraction |
| C-Sqr | ±20.000 mA - Square Root Extraction |

Select the input range that corresponds to the external signal. Before applying signal configure input jumper to match setting desired.

### ADC CONVERSION RATE

rAtE → 19.8

5.3 7.5 16.7 19.8
20 30 105

Select the ADC conversion rate. The selection does not affect the display update rate, (however it does affect setpoint response time). The default factory setting of 19.8 is recommended for most applications. Selecting a fast update rate may cause the display to appear very unstable.

### DISPLAY DECIMAL POINT

dECPt → 0.000

0 0.0 0.00 0.000 0.0000

Select the decimal point location for the Input display. (The **TOT** display decimal point is a separate parameter.) This selection also affects round, dSP 1 and dSP2 parameters and setpoint values.

### DISPLAY ROUNDING*

round → 0.001

1 2 5 10
20 50 100

Rounding selections other than one, cause the Input Display to 'round' to the nearest rounding increment selected (ie. rounding of '5' causes 121 to round to 120 and 124 to round to 125). Rounding starts at the least significant digit of the Input Display. Remaining parameter entries (scaling point values, setpoint values, etc.) are not automatically adjusted to this display rounding selection.

### FILTER SETTING

FILtr → 1.0

0.0 to 25.0 seconds

The input filter setting is a time constant expressed in tenths of a second. The filter settles to 99% of the final display value within approximately 3 time constants. This is an Adaptive Digital Filter which is designed to steady the Input Display reading. A value of '0' disables filtering.

### FILTER BAND*

bAnd → 0.0 10

0 to 250 display units

The digital filter will adapt to variations in the input signal. When the variation exceeds the input filter band value, the digital filter disengages. When the variation becomes less than the band value, the filter engages again. This allows for a stable readout, but permits the display to settle rapidly after a large process change. The value of the band is in display units, independent of the Display Decimal Point position. A band setting of '0' keeps the digital filter permanently engaged.

### SCALING POINTS

Pt5 → 2

2 to 16

#### Linear - Scaling Points (2)

For linear processes, only 2 scaling points are necessary. It is recommended that the 2 scaling points be at opposite ends of the input signal being applied. The points do not have to be the signal limits. Display scaling will be linear between and continue past the entered points up to the limits of the Input Signal Jumper position. Each scaling point has a coordinate-pair of Input Value ( InP) and an associated desired Display Value (dSP).

#### Square Root Extraction Input Range - Scaling Points (2)

The PAXDP can apply the square root function directly to the sensor signal by selecting the Square Root Extraction Input Range (U-Sqr or C-Sqr). When configured for Square Root Extraction, piecewise multipoint linearization is not required and only the first 2 scaling points are used. For proper operation the Display 1 (dSP 1) value must be zero.

#### Nonlinear - Scaling Points (Greater than 2)

For non-linear processes, up to 16 scaling points may be used to provide a piece-wise linear approximation. (The greater the number of scaling points used, the greater the conformity accuracy.) The Input Display will be linear between scaling points that are sequential in program order. Each scaling point has a coordinate-pair of Input Value ( InP) and an associated desired Display Value (dSP). Data from tables or equations, or empirical data could be used to derive the required number of segments and data values for the coordinate pairs.

### SCALING STYLE

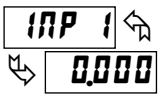
StyLE → KEY

KEY key-in data
APLY apply signal

If Input Values and corresponding Display Values are known, the Key-in (KEY) scaling style can be used. This allows scaling without the presence or changing of the input signal. If Input Values have to be derived from the actual input signal source or simulator, the Apply (APLY) scaling style must be used.

** The decimal point position is dependent on the selection made in the "Display Decimal Point" parameter.*

### INPUT VALUE FOR SCALING POINT 1




- 19.999 to 99.999

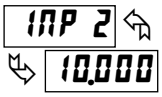
For Key-in (KEY), enter the known first Input Value by using the arrow keys. (The Input Range selection sets up the decimal location for the Input Value.) For Apply (APLY), apply the input signal to the meter, adjust the signal source externally until the desired Input Value appears. In either method, press the **PAR** key to enter the value being displayed. The **DSP** key can be pressed without changing the previously stored InP 1 value in the APLY style.

### DISPLAY VALUE FOR SCALING POINT 1*

- 19999 to 99999

Enter the first coordinating Display Value by using the arrow keys. This is the same for KEY and APLY scaling styles. The decimal point follows the dECPt selection. For Square Root Extraction Input Range, the Display 1 value must be zero.

### INPUT VALUE FOR SCALING POINT 2




- 19.999 to 99.999

For Key-in (KEY), enter the known second Input Value by using the arrow keys. For Apply (APLY), adjust the signal source externally until the next desired Input Value appears. (Follow the same procedure if using more than 2 scaling points.)

** The decimal point position is dependent on the selection made in the "Display Decimal Point" parameter.*

### DISPLAY VALUE FOR SCALING POINT 2*

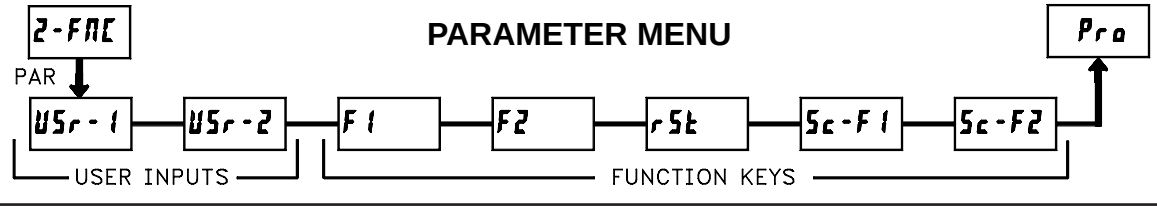
- 19999 to 99999

Enter the second coordinating Display Value by using the arrow keys. This is the same for KEY and APLY scaling styles. (Follow the same procedure if using more than 2 scaling points.)

### General Notes on Scaling

1. Input Values for scaling points should be confined to the limits of the Input Signal, ie. 4-20 mA or 0-10 VDC.
2. The same Input Value should not correspond to more than one Display Value. (Example: 20 mA can not equal 0 and 10.)
   This is referred to as readout jumps (vertical scaled segments).
3. The same Display Value can correspond to more than one Input Value. (Example: 0 mA and 20 mA can equal 10.)
   This is referred to as readout dead zones (horizontal scaled segments).
4. The maximum scaled Display Value spread between range maximum and minimum is limited to 65,535. For example using +20 mA range the maximum +20 mA can be scaled to is 32,767 with 0 mA being 0 and Display Rounding of 1. (Decimal points are ignored.) The other half of 65,535 is for the lower half of the range 0 to -20 mA even if it is not used. With Display Rounding of 2, +20 mA can be scaled for 65,535 (32,767 x 2) but with even Input Display values shown.
5. For input levels beyond the first programmed Input Value, the meter extends the Display Value by calculating the slope from the first two coordinate pairs ( InP 1 / dSP 1 & InP2 / dSP2). If InP 1 = 4 mA and dSP 1 = 0, then 0 mA would be some negative Display Value. This could be prevented by making InP 1 = 0 mA / dSP 1 = 0, InP2 = 4 mA / dSP2 = 0, with InP3 = 20 mA / dSP3 = the desired high Display Value. The calculations stop at the limits of the Input Range Jumper position.
6. For input levels beyond the last programmed Input Value, the meter extends the Display Value by calculating the slope from the last two sequential coordinate pairs. If three coordinate pair scaling points were entered, then the Display Value calculation would be between InP2 / dSP2 & InP3 / dSP3. The calculations stop at the limits of the Signal Input.

## 5.2 MODULE 2 - USER INPUT AND FRONT PANEL FUNCTION KEY PARAMETERS (2-FnC)



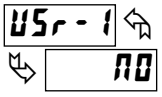

The two user inputs are individually programmable to perform specific meter control functions. While in the Display Mode or Program Mode, the function is executed the instant the user input transitions to the active state.

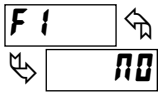
The front panel function keys are also individually programmable to perform specific meter control functions. While in the Display Mode or when viewing meter values in Quick Programming mode, the primary function is executed the instant the key is pressed. Holding the function key for three seconds executes a secondary function. It is possible to program a secondary function without a primary function.

In most cases, if more than one user input and/or function key is programmed for the same function, the maintained (level trigger) actions will be performed while at least one of those user inputs or function keys are activated. The momentary (edge trigger) actions will be performed every time any of those user inputs or function keys transition to the active state.

***Note:*** *In the following explanations, not all selections are available for both user inputs and front panel function keys. Alternating displays are shown with each selection. Those selections showing both displays are available for both. If a display is not shown, it is not available for that selection.* USr-1 *will represent both user inputs.* F1 *will represent all five function keys.*

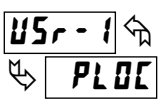
#### NO FUNCTION




No function is performed if activated. This is the factory setting for all user inputs and function keys. No function can be selected without affecting basic start-up.

#### PROGRAMMING MODE LOCK-OUT




Programming Mode is locked-out, as long as activated (maintained action). A security code can be configured to allow programming access during lock-out.

### INPUT A ZERO (TARE) DISPLAY

The Zero (Tare) Display provides a way to zero the Input A value at various input levels, causing future Display readings to be offset. This function is useful in weighing applications where the container or material on the scale should not be included in the next measurement value. When activated (momentary action), rESEt flashes and the Input A value is set to zero. At the same time, the Input A value (that was on the display before the Zero Display) is subtracted from the Input A Display Offset Value and is automatically stored as the new Display Offset Value (OFS-A). If another Zero (tare) Display is performed, the display will again change to zero and the Input A reading will shift accordingly.

### INPUT B ZERO (TARE) DISPLAY

The Zero (Tare) Display provides a way to zero the Input B value at various input levels, causing future Display readings to be offset. This function is useful in weighing applications where the container or material on the scale should not be included in the next measurement value. When activated (momentary action), rESEt flashes and the Input B value is set to zero. At the same time, the Input B value (that was on the display before the Zero Display) is subtracted from the Input B Display Offset Value and is automatically stored as the new Display Offset Value (OFS-b). If another Zero (tare) Display is performed, the display will again change to zero and the Input B reading will shift accordingly.

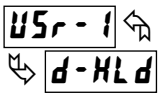
### INPUT A RELATIVE/ABSOLUTE DISPLAY

This function will switch the Input A Display between Relative and Absolute. The Relative is a net value that includes the Display Offset Value. The Input A Display will normally show the Relative unless switched by this function. The Absolute is a gross value (based on Module 1 **DSP** and **INP** entries) without the Display Offset Value. The Absolute display is selected as long as the user input is activated (maintained action) or at the transition of the function key (momentary action). When the user input is released, or the function key is pressed again, the input A display switches back to Relative display. AbS-A (absolute) or rEL-A (relative) is momentarily displayed at transition to indicate which display is active.

### INPUT B RELATIVE/ABSOLUTE DISPLAY

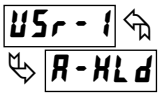
This function will switch the Input B Display between Relative and Absolute. The Relative is a net value that includes the Display Offset Value. The Input B Display will normally show the Relative unless switched by this function. The Absolute is a gross value (based on Module 1 **DSP** and **INP** entries) without the Display Offset Value. The Absolute display is selected as long as the user input is activated (maintained action) or at the transition of the function key (momentary action). When the user input is released, or the function key is pressed again, the input B display switches back to Relative display. AbS-A (absolute) or rEL-A (relative) is momentarily displayed at transition to indicate which display is active.

### HOLD DISPLAY



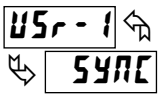

The shown display is held but all other meter functions continue as long as activated (maintained action).

### HOLD ALL FUNCTIONS




The meter disables processing the input, holds all display contents, and locks the state of all outputs as long as activated (maintained action). The serial port continues data transfer.

### SYNCHRONIZE METER READING




The meter suspends all functions as long as activated (maintained action). When the user input is released, the meter synchronizes the restart of the A/D's with other processes or timing events.

---

Input assignment for the totalizer is programmed in Module 5, Totalizer (Integrator) Parameters. Only the assigned input or calculation will be active for the following Totalizer User Functions.

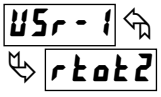
### STORE BATCH READING IN TOTALIZER

The assigned value is one time added (batched) to the Totalizer at transition to activate (momentary action). The Totalizer retains a running sum of each batch operation until the Totalizer is reset. When this function is selected, the normal operation of the Totalizer is overridden.

### RESET TOTALIZER

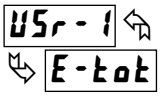
When activated (momentary action), rESEt flashes and the Totalizer resets to zero. The Totalizer then continues to operate as it is configured. This selection functions independent of the selected display.

### RESET AND ENABLE TOTALIZER




When activated (momentary action), rESEt flashes and the Totalizer resets to zero. The Totalizer continues to operate while active (maintained action). When the user input is released, the Totalizer stops and holds its value. This selection functions independent of the selected display.

### ENABLE TOTALIZER




The Totalizer continues to operate as long as activated (maintained action). When the user input is released, the Totalizer stops and holds its value. This selection functions independent of the selected display.

### RESET MAXIMUM

When activated (momentary action), rESEt flashes and the Maximum resets to the present assigned value. The Maximum function then continues from that value. This selection functions independent of the selected display.

### RESET MINIMUM

When activated (momentary action), rESEt flashes and the Minimum reading is set to the present assigned value. The Minimum function then continues from that value. This selection functions independent of the selected display.

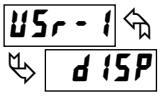
### RESET MAXIMUM AND MINIMUM

When activated (momentary action), rESEt flashes and the Maximum and Minimum readings are set to the present assigned values. The Maximum and Minimum function then continues from that value. This selection functions independent of the selected display.

---

Note: Following display functions are only available on User Input.

### ADVANCE DISPLAY




When activated (momentary action), the display advances to the next display that is not locked out from the Display Mode.

### SELECT DISPLAY A

When activated (momentary action), the display advances to Display A, if enabled.

### SELECT DISPLAY B

When activated (momentary action), the display advances to Display B, if enabled.

### SELECT DISPLAY C

When activated (momentary action), the display advances to Display C, if enabled.

### SELECT DISPLAY _

When activated (momentary action), the display advances to the Display _ (no annunciator), if enabled.

---

### CHANGE DISPLAY INTENSITY LEVEL

When activated (momentary action), the display intensity changes to the next intensity level (of 4). The four levels correspond to Display Intensity Level (d-LEu) settings of 0, 3, 8, and 15.

### SETPOINT SELECTIONS

The following selections are functional only with the Setpoint plug-in card installed. Refer to the Setpoint Card Bulletin shipped with the Setpoint plug-in card for an explanation of their operation.

**Setpoint Card Only**

- **L ISt - Select main or alternate setpoints**
- **r-1 - Reset Setpoint 1 (Alarm 1)**
- **r-2 - Reset Setpoint 2 (Alarm 2)**
- **r-3 - Reset Setpoint 3 (Alarm 3)**
- **r-4 - Reset Setpoint 4 (Alarm 4)**
- **r-34 - Reset Setpoint 3 & 4 (Alarm 3 & 4)**
- **r-234 - Reset Setpoint 2, 3 & 4 (Alarm 2, 3 & 4)**
- **r-ALL - Reset Setpoint All (Alarm All)**

### EXCHANGE PARAMETER LISTS

Two lists of values are available for SP-1, SP-2, SP-3, SP-4. The two lists are named LSt-A and LSt-b. If a user input is used to select the list then LSt-A is selected when the user input is not active and and LSt-b is selected when the user input is active (maintained action). If a front panel key is used to select the list then the list will toggle for each key press (momentary action). The display will only indicate which list is active when the list is changed.

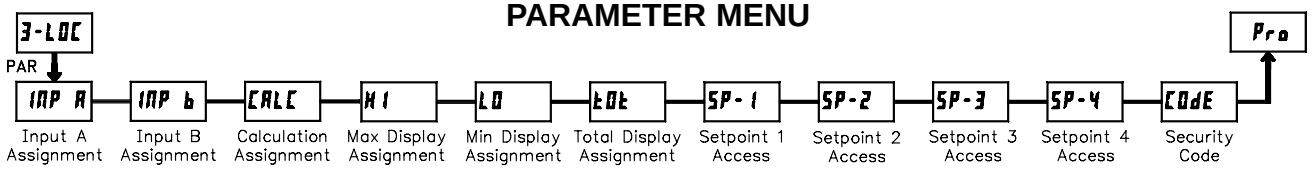
To program the values for LSt-A and LSt-b, first complete the programming of all the parameters. Exit programming and switch to the other list. Re-enter programming and enter the values for SP-1, SP-2, SP-3, SP-4. If any other parameters are changed then the other list values must be reprogrammed.

### PRINT REQUEST

The meter issues a block print through the serial port when activated, and the serial type is set to rLC. The data transmitted during a print request and the serial type is programmed in Module 7. If the user input is still active after the transmission is complete (about 100 msec), an additional transmission occurs. As long as the user input is held active, continuous transmissions occur.

# 5.3 MODULE 3 - DISPLAY ASSIGNMENT AND PROGRAM LOCK-OUT PARAMETERS (3-LOC)

## PARAMETER MENU

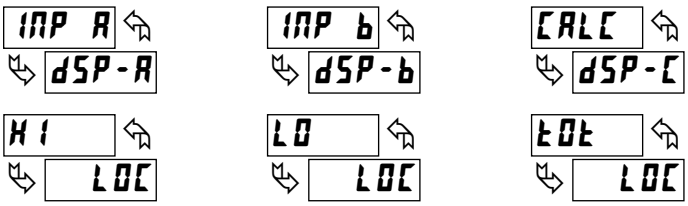



Module 3 is the programming for the Display, Display assignments, Display lock-out and "Full" and "Quick" Program lock-out.

When in the main Display Mode, the available displays (A,B,C,_) can be read consecutively by repeatedly pressing the **DSP** key. An annunciator indicates the display being shown (_ = No annunciator). A meter display value can be programmed to one of the displays, to the quick programming mode or be locked from being visible. It is recommended that the meter display value be set to LOC when it is not being used in the application.

"Full" Programming Mode permits all parameters to be viewed and modified. This Programming Mode can be locked with a security code and/or user input. When locked and the PAR key is pressed, the meter enters a Quick Programming Mode. In this mode, the setpoint values can still be read and/or changed per the selections below. The display Intensity Level (d-LEU) parameter also appears whenever Quick Programming Mode is enabled and the security code greater than zero.

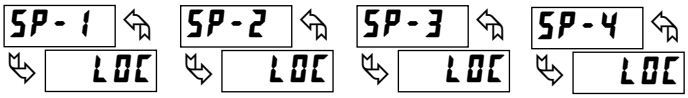
### DISPLAY ASSIGNMENT




There are six meter values that can be individually programmed for one of the main displays (A,B,C or _), or programmed to be viewable in Quick Programming mode (rEd), or programmed to be locked out from display (LOC) (see the following table). If two or more values are assigned to the same display the last value assigned will be the one that is displayed.

| | |
|---|---|
| LOC | Not visible in Display Mode or Quick Programming Mode |
| rEd | Visible in Quick Programming Mode only |
| dSP-_ | Assign to Display _ (No annunciator) |
| dSP-A | Assign to Display A |
| dSP-b | Assign to Display B |
| dSP-C | Assign to Display C |

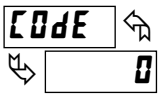
### SP-1 SP-2 SP-3 SP-4 SETPOINT ACCESS*




The setpoint displays can be programmed for LOC, rEd or Ent (see the following table). Accessible only with the Setpoint plug-in card installed.

| SELECTION | DESCRIPTION |
|---|---|
| LOC | Not visible in Quick Programming Mode Only |
| rEd | Visible in Quick Programming Mode Only |
| Ent | Visible and changeable in Quick Programming Mode Only |

### PROGRAM MODE SECURITY CODE*




0 to 250

By entering any non-zero value, the prompt CodE 0 will appear when trying to access the Program Mode. Access will only be allowed after entering a matching security code or universal code of 222. With this lock-out, a user input would not have to be configured for Program Lock-out. However, this lock-out is overridden by an inactive user input configured for Program Lock-out.

***** *Factory Setting can be used without affecting basic start-up.*

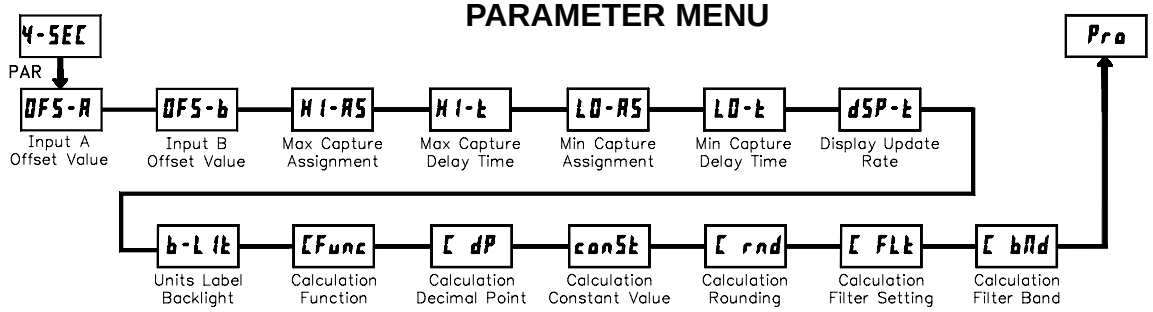
### PROGRAMMING MODE ACCESS

| SECURITY CODE | USER INPUT CONFIGURED | USER INPUT STATE | WHEN PAR KEY IS PRESSED | "FULL" PROGRAMMING MODE ACCESS |
|---|---|---|---|---|
| 0 | not PLOC | ———— | "Full" Programming | Immediate access. |
| >0 | not PLOC | ———— | Quick Programming w/Display Intensity | After Quick Programming with correct code # at CodE prompt. |
| >0 | PLOC | Active | Quick Programming w/Display Intensity | After Quick Programming with correct code # at CodE prompt. |
| >0 | PLOC | Not Active | "Full" Programming | Immediate access. |
| 0 | PLOC | Active | Quick Programming | No access |
| 0 | PLOC | Not Active | "Full" Programming | Immediate access. |

Throughout this document, Programming Mode (without Quick in front) always refers to "Full" Programming (all meter parameters are accessible).

# 5.4 MODULE 4 - SECONDARY FUNCTION PARAMETERS (4-SEC)

## PARAMETER MENU




### INPUT A OFFSET VALUE*

OFS-A / 0.000 — -19999 to 19999

Unless a Zero Display was performed or an offset from Module 1 scaling is desired for Input A, this parameter can be skipped. The Display Offset Value is the difference between the Absolute (gross) Display value and the Relative (net) Display value for the same input level. The meter will automatically update this Display Offset Value after each Zero Display. The Display Offset Value can be directly keyed-in to intentionally add or remove display offset. See Relative / Absolute Display and Zero Display explanations in Module 2.

### INPUT B OFFSET VALUE*

OFS-b / 0.000 — -19999 to 19999

Unless a Zero Display was performed or an offset from Module 1 scaling is desired for Input B, this parameter can be skipped. The Display Offset Value is the difference between the Absolute (gross) Display value and the Relative (net) Display value for the same input level. The meter will automatically update this Display Offset Value after each Zero Display. The Display Offset Value can be directly keyed-in to intentionally add or remove display offset. See Relative / Absolute Display and Zero Display explanations in Module 2.

### MAX CAPTURE ASSIGNMENT

HI-AS / A-rEL — A-rEL A-Ab5 b-rEL b-Ab5 CALC

Select the desired parameter that will be assigned to the Max Capture.

### MAX CAPTURE DELAY TIME

HI-t / 1.0 — 0.0 to 3275.0 sec.

When the Input Display is above the present MAX value for the entered delay time, the meter will capture that display value as the new MAX reading. A delay time helps to avoid false captures of sudden short spikes.

### MIN CAPTURE ASSIGNMENT

LO-AS / A-rEL — A-rEL A-Ab5 b-rEL b-Ab5 CALC

Select the desired parameter that will be assigned to the Min Capture.

### MIN CAPTURE DELAY TIME

LO-t / 1.0 — 0.0 to 3275.0 sec.

When the Input Display is below the present MIN value for the entered delay time, the meter will capture that display value as the new MIN reading. A delay time helps to avoid false captures of sudden short spikes.

### DISPLAY UPDATE RATE

dSP-t / 1 — 1 2 5 10 20 updates/sec.

This parameter determines the rate of display update.

### UNITS LABEL BACKLIGHT

b-LIt / OFF — ON OFF

The Units Label Kit Accessory contains a sheet of custom unit overlays which can be installed in to the meter's bezel display assembly. The backlight for these custom units is activated by this parameter.

### CALCULATION FUNCTION

CFunc / c+a+b — c+A+b c-A-b c+A-b ab/c cA/b c(A/B-1)

This parameter determines the math calculation that will be performed on Input A and Input B and shown on the calculation display. The above formulas represent the available calculations; A = Input A relative value, b = Input B relative value, and c = Calculation Constant Value (conSt). The Input A & B decimal point locations do not affect the math function.

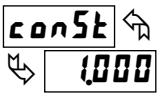
### CALCULATION DECIMAL POINT

C dP / 0.000 — 0 0.0 0.00 0.000 0.0000

This parameter determines the decimal point location for the Calculation Display.

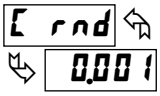
** The decimal point position is dependent on the selection made in the "Display Decimal Point" parameter.*

### CALCULATION CONSTANT VALUE




The constant value is used in the Calculation Function formulas to provide offsetting or scaling capabilities. For the C+A+b, C-A-b, and C+A-b calculation functions, the Constant decimal point matches that Calculation Decimal point position.

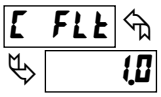
### CALCULATION ROUNDING*




1 2 5 10
20 50 100

Rounding selections other than one, cause the Calculation Display to 'round' to the nearest rounding increment selected (ie. rounding of '0.005' causes 0.121 to round to 0.120 and 0.124 to round to 125). Rounding starts at the least significant digit of the Calculation Display. Remaining parameter entries (scaling point values, setpoint values, etc.) are not automatically adjusted to this display rounding selection. The displayed decimal point reflects that programmed in **C dP**.

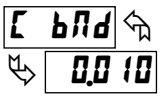
### CALCULATION FILTER SETTING




0.0 to 25.0

The calculation filter setting is a time constant expressed in tenths of a second. The filter settles to 99% of the final display value within approximately 3 time constants. This is an Adaptive Digital Filter which is designed to steady the Calculation Display reading. A value of '0' disables filtering.

### CALCULATION FILTER BAND*

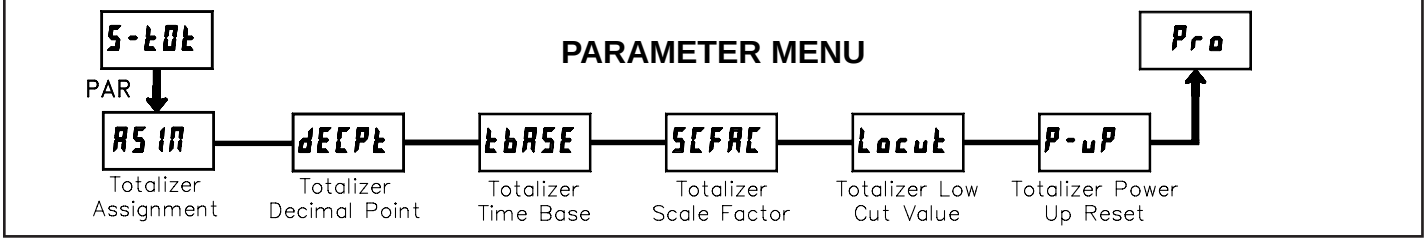



0 to 250 display units

The digital filter will adapt to variations in the calculation filter. When the variation exceeds the calculation filter band value, the digital filter disengages. When the variation becomes less than the band value, the filter engages again. This allows for a stable readout, but permits the display to settle rapidly after a large process change. The value of the band is in display units, independent of the Display Decimal Point position. A band setting of '0' keeps the digital filter permanently engaged.

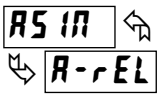
** The decimal point position is dependent on the selection made in the "Calculation Decimal Point" parameter.*

## 5.5 MODULE 5 - TOTALIZER (INTEGRATOR) PARAMETERS (5-tOt)




The totalizer accumulates (integrates) the relative Input value using one of two modes. The first is using a time base. This can be used to provide an indication of total flow, usage or consumption over time. The second is through a user input or function key programmed for Batch (one time add on demand). This can be used for weighing applications where accumulation is based on a completed event. If the Totalizer is not needed, its display can be locked-out and this module can be skipped during programming.

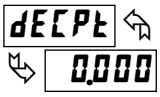
### TOTALIZER ASSIGNMENT




A-rEL b-rEL CALC

This parameter determines which value is to be totalized.

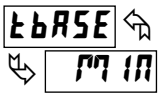
### TOTALIZER DECIMAL POINT*




0 0.0 0.00 0.000 0.0000

For most applications, this should match the decimal point position of the meter value selected in the totalizer assignment. If a different location is desired, refer to Totalizer Scale Factor.

### TOTALIZER TIME BASE




SEC - seconds (÷ 1) hour - hours (÷ 3600)
PM IN - minutes (÷ 60) dAY - days (÷ 86400)

This is the time base used in Totalizer accumulations. If the Totalizer is being accumulated through a user input programmed for Batch, then this parameter does not apply.

### TOTALIZER SCALE FACTOR*

0.001 to 65.000

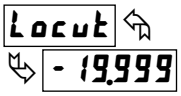
For most applications, the Totalizer reflects the same decimal point location and engineering units as the assigned Input Display. In these cases, the Totalizer Scale Factor is 1.000. The Totalizer Scale Factor can be used to scale the Totalizer to a different value than the Input Display. Common possibilities are:

1. Changing decimal point location (example tenths to whole)
2. Average over a controlled time frame.

Details on calculating the scale factor are shown later.

If the Totalizer is being accumulated through a user input programmed for Batch, then this parameter does not apply.

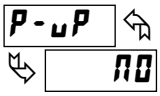
## TOTALIZER LOW CUT VALUE*




-19999 to 99999

A low cut value disables Totalizer when the Input Display value falls below the value programmed.

## TOTALIZER POWER UP RESET




| | |
|---|---|
| no | Do not reset totalizer |
| YES | Reset totalizer |

The Totalizer can be reset to zero on each meter power-up by setting this parameter to reset.

** The decimal point position is dependent on the selection made in the "Totalizer Decimal Point" parameter.*

## TOTALIZER HIGH ORDER DISPLAY

When the total exceeds 5 digits, the front panel annunciator flashes (if assigned to A, B, or C display). In this case, the meter continues to totalize up to a 9 digit value. The high order 4 digits and the low order 5 digits of the total are displayed alternately. The letter "h" denotes the high order display.

## TOTALIZER BATCHING

The Totalizer Time Base and scale factor are overridden when a user input or function key is programmed for store batch (bAtt). In this mode, when the user input or function key is activated, the Input Display reading is one time added to the Totalizer (batch). The Totalizer retains a running sum of each batch operation until the Totalizer is reset. This is useful in weighing operations, when the value to be added is not based on time but after a filling event.

## TOTALIZER USING TIME BASE

Totalizer accumulates as defined by:

$$\frac{\text{Input Display} \times \text{Totalizer Scale Factor}}{\text{Totalizer Time Base}}$$

Where:
- Input Display - the present input reading
- Totalizer Scale Factor - 0.001 to 65.000
- Totalizer Time Base - (the division factor of tbASE)

Example: The input reading is at a constant rate of 10.0 gallons per minute. The Totalizer is used to determine how many gallons in tenths has flowed. Because the Input Display and Totalizer are both in tenths of gallons, the Totalizer Scale Factor is 1. With gallons per minute, the Totalizer Time Base is minutes (60). By placing these values in the equation, the Totalizer will accumulate every second as follows:

$\frac{10.0 \times 1.000}{60}$ = 0.1667 gallon accumulates each second

This results in:
10.0 gallons accumulates each minute
600.0 gallons accumulates each hour

## TOTALIZER SCALE FACTOR CALCULATION EXAMPLES

1. When changing the Totalizer Decimal Point (dECPt) location from the Input Display Decimal Point (dECPt), the required Totalizer Scale Factor is multiplied by a power of ten.

Example: Input (dECPt) = 0.0

| Totalizer dECPt | Scale Factor |
|---|---|
| 0.00 | 10 |
| 0.0 | 1 |
| 0 | .1 |
| x10 | .01 |
| x100 | .001 |

Input (dECPt) = 0.00

| Totalizer dECPt | Scale Factor |
|---|---|
| 0.000 | 10 |
| 0.00 | 1 |
| 0.0 | .1 |
| 0 | .01 |
| x10 | .001 |

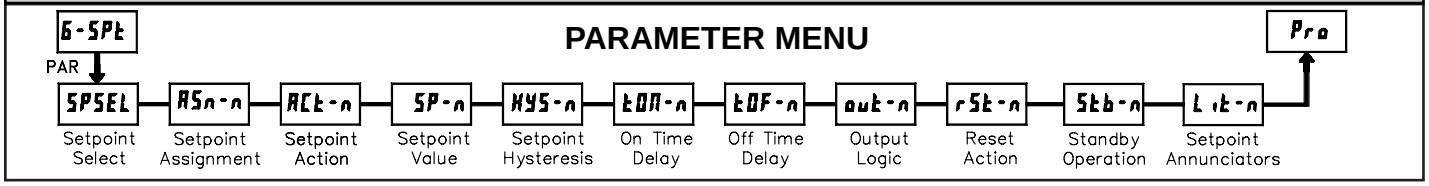
*(x = Totalizer display is round by tens or hundreds)*

2. To obtain an average reading within a controlled time frame, the selected Totalizer Time Base is divided by the given time period expressed in the same timing units.

Example: Average flow rate per hour in a 4 hour period, the scale factor would be 0.250. To achieve a controlled time frame, connect an external timer to a user input programmed for rtot2. The timer will control the start (reset) and the stopping (hold) of the totalizer.

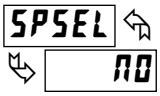
Modules 6, 7, and 8 are accessible only with the appropriate plug-in cards installed. A quick overview of Modules 6 & 8 is listed below. Refer to the corresponding plug-in card bulletin for a more detailed explanation of each parameter selection.

# 5.6 MODULE 6 - SETPOINT (ALARM) PARAMETERS (6-SPt)




**Repeat programming for each setpoint.**

### SELECT SETPOINT

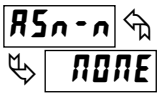



no SP-1 SP-3
SP-2 SP-4

Select a setpoint (alarm output) to open the remaining module menu. (The "n" in the following parameters will reflect the chosen setpoint number.) After the chosen setpoint is programmed, the display will default to SPSEL no. Select the next setpoint to be programmed and continue the sequence for each setpoint. Pressing **PAR** at SPSEL no will exit Module 6.

The parameters listed below are different from those listed in the Setpoint Card Literature. Use the Refer to Setpoint Option Card Literature for all other setpoint parameters.

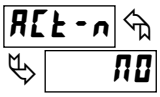
### SETPOINT ASSIGNMENT




NONE A-rEL A-Ab5 b-rEL
b-Ab5 CALC tot

Selects the meter value that is used to trigger the Setpoint Alarm. The -rEL settings cause the setpoint to trigger off of the relative (net) input value. The -AbS settings cause the setpoint to trigger off of the absolute (gross) input value.

### SETPOINT ACTION




no Ab-H1 Ab-LO AU-H1
AU-LO dE-H1 * dE-LO * bAnd *
bnd in totLo ** toth1 **

Enter the action for the selected setpoint (alarm output).

See Setpoint Alarm Figures in the Setpoint Card Literature for a visual detail of each action.

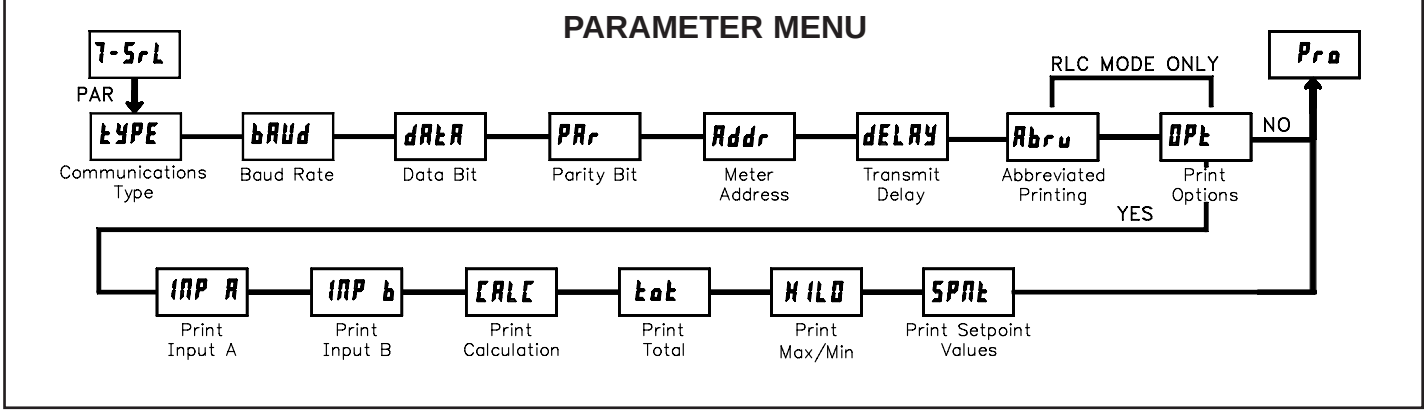
- no = No Setpoint Action
- Ab-H1 = Absolute high, with balanced hysteresis
- Ab-LO = Absolute low, with balanced hysteresis
- AU-H1 = Absolute high, with unbalanced hysteresis
- AU-LO = Absolute low, with unbalanced hysteresis
- dE-H1 = Deviation high, with unbalanced hysteresis *
- dE-LO = Deviation low, with unbalanced hysteresis *
- bAnd = Outside band, with unbalanced hysteresis *
- bnd in = Inside band, with unbalanced hysteresis *
- totLo = Lower Totalizer absolute high, unbalance hysteresis **
- totH1 = Upper Totalizer absolute high, unbalance hysteresis **

* Setpoint 2 or Setpoint 4 deviation and band action setpoints are relative to the value of setpoint 1 or Setpoint 3 respectively. It is not possible to configure setpoint 1 or 3 as deviation or band actions. It is possible to use setpoint 1 or 3 for an absolute action, while its value is being used for deviation or band.

** These modes only appear, and are the only modes that appear, when the setpoint assignment ASn-n is set to tot. The lower Totalizer action, totLo, allows setpoints to function off of the lower 5 digits of the Totalizer. The upper Totalizer action, toth1, allows setpoints to function off of the upper 4 digits of the Totalizer. To obtain absolute low alarms for the Totalizer, program the totLo or toth1 output logic as reverse.

| | |
|---|---|
| SP-n - SETPOINT VALUE | -19999 to 99999 |
| HYS-n - SETPOINT HYSTERESIS | 1 to 65000 |
| tON-n - ON TIME DELAY | 0.0 to 3275.0 sec |
| tOF-n - OFF TIME DELAY | 0.0 to 3275.0 sec |
| out-n - OUTPUT LOGIC | nor rEu |
| rSt-n - RESET ACTION | AUto LAtC2<br>LAtC1 |
| Stb-n - STANDBY OPERATION | no YES |
| L it-n - SETPOINT ANNUNCIATORS | OFF rEu<br>nor FLASH |

# 5.7 MODULE 7 - SERIAL COMMUNICATIONS PARAMETERS (7-SrL)




Module 7 is the programming module for the Serial Communications Parameters. These parameters are used to match the serial settings of the PAXDP with those of the host computer or other serial device, such as a terminal or printer. This programming module can only be accessed if an RS232 or RS485 Serial Communications card is installed.

This section also includes an explanation of the commands and formatting required for communicating with the PAXDP. In order to establish serial communications, the user must have host software that can send and receive ASCII characters or utilizes Modbus protocol. For serial hardware and wiring details, refer to section 3.6 Serial Communication Wiring.

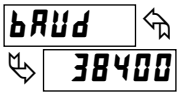
*This section replaces the bulletin shipped with the RS232 and RS485 serial communications plug-in cards. Discard the separate bulletin when using those serial plug-in cards with the PAXDP. Also, this section does NOT apply to the DeviceNet, or Profibus-DP communication cards. For details on the operation of the Fieldbus cards, refer to the bulletin shipped with each card.*

### COMMUNICATIONS TYPE

rLC - RLC Protocol
Mbrt - Modbus RTU
MbAS - Modbus ASCII

Select the desired communications protocol. Modbus is preferred as it provides access to all meter values and parameters. Since the Modbus protocol is included within the PAXDP, the PAX Modbus option card, PAXCDC4, should not be used. The PAXCDC1 (RS485), or PAXCDC2 (RS232) card should be used instead.

### BAUD RATE




300 600 1200 2400
4800 9600 19200 38400

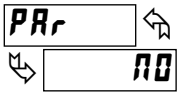
Set the baud rate to match the other serial communications equipment on the serial link. Normally, the baud rate is set to the highest value that all the serial equipment are capable of transmitting and receiving.

### DATA BIT

7 8

Select either 7 or 8 bit data word lengths. Set the word length to match the other serial communications equipment on the serial link.

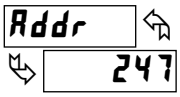
### PARITY BIT




nO EVEN Odd

Set the parity bit to match that of the other serial communications equipment on the serial link. The meter ignores the parity when receiving data and sets the parity bit for outgoing data. If no parity is selected with 7 bit word length, an additional stop bit is used to force the frame size to 10 bits.

### METER UNIT ADDRESS




00 to 99 (RLC Protocol)
1 to 247 (Modbus)

Enter the serial meter (node) address. The address range is dependent on the tYPE parameter. With a single unit, configured for RLC protocol (tYPE = rLC), an address is not needed and a value of zero can be used. With multiple units (RS485 applications), a unique 2 digit address number must be assigned to each meter.

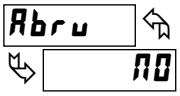
### TRANSMIT DELAY

0.0 10 to 0.250

Following a transmit value ('*' terminator) or Modbus command, the PAXDP will wait this minimum amount of time in seconds before issuing a serial response.

Parameters below only appear when communications type (tYPE) parameter is set to rLC.

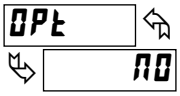
### ABBREVIATED PRINTING




YES NO

Select no for full print or Command T transmissions (meter address, parameter data and mnemonics) or YES for abbreviated print transmissions (parameter data only). This will affect all the parameters selected in the print options. (If the meter address is 00, it will not be sent during a full transmission.)

### PRINT OPTIONS




YES - Enters the sub-menu to select the meter parameters to appear during a print request. For each parameter in the sub-menu, select YES for that parameter information to be sent during a print request or no for that parameter information not to be sent. A print request is sometimes referred to as a block print because more than one parameter information (meter address, parameter data and mnemonics) can be sent to a printer or computer as a block.

| PARAMETER | DESCRIPTION |
|---|---|
| inP A | Input A Value |
| inP b | Input B Value |
| CALC | Calculation |
| tot | Total Value |
| HILO | Max. & Min. |
| SPnt | Setpoint Values |

---

# SERIAL MODBUS COMMUNICATIONS

Modbus Communications requires that the Serial Communication Type Parameter (tYPE) be set to "rtu" or "bAS".

## SUPPORTED FUNCTION CODES

### FC03: Read Holding Registers

1. Up to 32 registers can be requested at one time.
2. HEX <8000> is returned for non-used registers.

### FC04: Read Input Registers

1. Up to 32 registers can be requested at one time.
2. Block starting point can not exceed register boundaries.
3. HEX <8000> is returned in registers beyond the boundaries.
4. Input registers are a mirror of Holding registers.

### FC06: Preset Single Register

1. HEX <8001> is echoed back when attempting to write to a read only register.
2. If the write value exceeds the register limit (see Register Table), then that register value changes to its high or low limit. It is also returned in the response.

### FC16: Preset Multiple Registers

1. No response is given with an attempt to write to more than 32 registers at a time.
2. Block starting point cannot exceed the read and write boundaries (40001-41280).
3. If a multiple write includes read only registers, then only the write registers will change.
4. If the write value exceeds the register limit (see Register Table), then that register value changes to its high or low limit.

### FC08: Diagnostics

The following is sent upon FC08 request:

Module Address, 08 (FC code), 04 (byte count), "Total Comms" 2 byte count, "Total Good Comms" 2 byte count, checksum of the string

"Total Comms" is the total number of messages received that were addressed to the PAXDP. "Total Good Comms" is the total messages received by the PAXDP with good address, parity and checksum. Both counters are reset to 0 upon response to FC08 and at power-up.

### FC17: Report Slave ID

The following is sent upon FC17 request:

RLC-PAXDP ab<0100h><20h><20h><10h>

- 16 Guid/Scratch Pad
- Max Register Reads (32)
- Max Register Writes (32)
- Software Version Number
- b = Linear Card "0" = None, "1" = Yes
- a = SP Card, "0"-No SP, "2" or "4" SP

a = "0"(none), "2", "4" SP card installed

b = "0"(none) or "1" Linear Card installed),

## SUPPORTED EXCEPTION CODES

### 01: Illegal Function

Issued whenever the requested function is not implemented in the meter.

### 02: Illegal Data Address

Issued whenever an attempt is made to access a single register that does not exist (outside the implemented space) or to access a block of registers that falls completely outside the implemented space.

### 03: Illegal Data Value

Issued when an attempt is made to read or write more registers than the meter can handle in one request.

### 07: Negative Acknowledge

Issued when a write to a register is attempted with an invalid string length.

## *PAXDP MODBUS REGISTER TABLE*

The below limits are shown as Integers or HEX < > values. Read and write functions can be performed in either Integers or Hex as long as the conversion was done correctly. Negative numbers are represented by two's complement.

Note 1: The PAXDP should not be powered down while parameters are being changed. Doing so may corrupt the non-volatile memory resulting in checksum errors.

| REGISTER ADDRESS [1] | REGISTER NAME | LOW LIMIT [2] | HIGH LIMIT [2] | FACTORY SETTING | ACCESS | COMMENTS |
|---|---|---|---|---|---|---|
| | **FREQUENTLY USED REGISTERS** | | | | | |
| 40001 | Input A Relative Value (Hi word) | N/A | N/A | N/A | Read Only | Process value of present input level. This value is affected by Input Type, Resolution, Scaling & Offset Value (Relative Value = Absolute Input Value + Offset Value) |
| 40002 | Input A Relative Value (Lo word) | | | | | |
| 40003 | Input B Relative Value (Hi word) | N/A | N/A | N/A | Read Only | Process value of present input level. This value is affected by Input Type, Resolution, Scaling & Offset Value (Relative Value = Absolute Input Value + Offset Value) |
| 40004 | Input B Relative Value (Lo word) | | | | | |
| 40005 | Calculation Value (Hi word) | N/A | N/A | N/A | Read Only | Calculation Result of Math Function |
| 40006 | Calculation Value (Lo word) | | | | | |
| 40007 | Maximum Value (Hi word) | N/A | N/A | N/A | Read Only | |
| 40008 | Maximum Value (Lo word) | | | | | |
| 40009 | Minimum Value (Hi word) | N/A | N/A | N/A | Read Only | |
| 40010 | Minimum Value (Lo word) | | | | | |
| 40011 | Total Value (Hi word) | N/A | N/A | N/A | Read Only | |
| 40012 | Total Value (Lo word) | | | | | |
| 40013 | Setpoint 1 Value (Hi word) | -19999 | 99999 | 100 | Read/Write | |
| 40014 | Setpoint 1 Value (Lo word) | | | | | |
| 40015 | Setpoint 2 Value (Hi word) | -19999 | 99999 | 200 | Read/Write | |
| 40016 | Setpoint 2 Value (Lo word) | | | | | |
| 40017 | Setpoint 1 Value (Hi word) | -19999 | 99999 | 300 | Read/Write | |
| 40018 | Setpoint 1 Value (Lo word) | | | | | |
| 40019 | Setpoint 2 Value (Hi word) | -19999 | 99999 | 400 | Read/Write | |
| 40020 | Setpoint 2 Value (Lo word) | | | | | |
| 40021 | Setpoint Output Register (SOR) | 0 | 15 | N/A | Read/Write See Note | Status of Setpoint Outputs: Bit State: 0=Off, 1=On, Bit 3 = SP1, Bit 2 = SP2, Bit 1 = SP3, Bit 0 = SP4 Outputs can only be activated/reset with this register when respective bits in Manual Mode (MMR) register are set |
| 40022 | Manual Mode Register (MMR) | 0 | 31 | 0 | Read/Write | Bit State: 0=Auto Mode, 1=Manual Mode Bit 4 = SP1, Bit 3 = SP2, Bit 2 = SP3, Bit 1 = SP4, Bit 0 = Linear Output |
| 40023 | Reset Output Register | 0 | 15 | 0 | Read/Write | Bit State: 1= Reset Output; Bit is returned to zero following reset processing Bit 3 = SP1, Bit 2 = SP2, Bit 1 = SP3, Bit 0 = SP4 |
| 40024 | Analog Output Register (AOR) | 0 | 4095 | 0 | Read/Write | Functional only if Linear Output is in manual mode (MMR bit 0 = 1). Linear Output Card is written to only if Linear Out (MMR bit 0) is set |
| 40025 | Input A Absolute Value (Hi word) | N/A | N/A | N/A | Read Only | Gross value of present Input A level. This value is affected by Input Type, Resolution, Scaling, but not affected by Offset Value |
| 40026 | Input A Absolute Value (Lo word) | | | | | |
| 40027 | Input B Absolute Value (Hi word) | N/A | N/A | N/A | Read Only | Gross value of present Input B level. This value is affected by Input Type, Resolution, Scaling, but not affected by Offset Value |
| 40028 | Input B Absolute Value (Lo word) | | | | | |
| 40029 | Input A Offset Value (Hi word) | -19999 | 99999 | 0 | Read/Write | Relative Input Value (standard meter value) is sum of Input Offset Value and Input Absolute Value |
| 40030 | Input A Offset Value (Lo word) | | | | | |
| 40031 | Input B Offset Value (Hi word) | -19999 | 99999 | 0 | Read/Write | Relative Input Value (standard meter value) is sum of Input Offset Value and Input Absolute Value |
| 40032 | Input B Offset Value (Lo word) | | | | | |

[1] For Input Registers, replace the 4xxxx with a 3xxxx in the above register address. The 3xxxx are a mirror of the 4xxxx Holding Registers.
[2] An attempt to exceed a limit will set the register to its high or low limit value.

| REGISTER ADDRESS [1] | | REGISTER NAME | LOW LIMIT [2] | HIGH LIMIT [2] | FACTORY SETTING | ACCESS | COMMENTS |
|---|---|---|---|---|---|---|---|
| CH A | CH B | **INPUT PARAMETERS** | | | | | **SEE MODULE 1 FOR DESCRIPTION OF PARAMETERS** |
| 40101 | 40201 | Input Range | 0 | 1 | 0 | Read/Write | 0=Volt, 1=Current, 2=Volt Square Root Extraction, 3= Current Square Root Extraction |
| 40102 | 40202 | ADC Conversion Rate (samples/sec) | 0 | 6 | 3 | Read/Write | 0=5.3, 1=7.5, 2=16.7, 3=19.8, 4=20, 5=30, 6=105 |
| 40103 | 40203 | Decimal Point | 0 | 4 | 3 | Read/Write | 0=0, 1=0.0, 2=0.00, 3=0.000, 4=0.0000 |
| 40104 | 40204 | Rounding Factor | 0 | 6 | 0 | Read/Write | 0=1, 1=2, 2=5, 3=10, 4=20, 5=50, 6=100 |
| 40105 | 40205 | Digital Input Filter | 0 | 250 | 10 | Read/Write | 1=0.1 Second |
| 40106 | 40206 | Filter Band | 0 | 250 | 10 | Read/Write | 1=1 display unit |
| 40107 | 40207 | Number of Scaling Points | 2 | 16 | 2 | Read/Write | Number of LInearization Scaling Points |
| 40108 | 40208 | Reserved | N/A | N/A | N/A | N/A | |
| | | **SCALING POINTS PARAMETERS** | | | | | |
| 40109 | 40209 | Input 1 Input Value (Hi word) | -19999 | 99999 | 0 | Read/Write | 1=0.001 |
| 40110 | 40210 | Input 1 Input Value (Lo word) | | | | | |
| 40111 | 40211 | Display 1 Input Value (Hi word) | -19999 | 99999 | 0 | Read/Write | |
| 40112 | 40212 | Display 1 Input Value (Lo word) | | | | | |
| thru | thru | | ... | ... | ... | ... | Registers 40113-40168, 40213-40268 not shown but follow ordering as shown for Input 1, Display 1 |
| 40169 | 40269 | Input 16 Input Value (Hi word) | -19999 | 99999 | 0 | Read/Write | 1=0.001 |
| 40170 | 40270 | Input 16 Input Value (Lo word) | | | | | |
| 40171 | 40271 | Input 16 Input Value (Hi word) | -19999 | 99999 | 0 | Read/Write | |
| 40172 | 40272 | Input 16 Input Value (Lo word) | | | | | |
| | | **USER INPUT/FUNCTION KEYS** | | | | | **SEE MODULE 2 FOR DESCRIPTIONS OF PARAMETERS** |
| 40301 | | User Input 1 Action | 0 | 30 | 0 | Read/Write | 0= NO, 1 = PLOC, 2 = A-rEL, 3 = b-rEL, 4 = A-drL, 5 = b-drL, 6 = d-HLd, 7 = A-HLd, 8 = SYNC, 9 = bAt, 10 = rtot1, 11 = rtot2, 12 = E-tot, 13 = r-HI, 14 = r-Lo, 15 = r-HL, 16 = dISP, 17 = dSP-A, 18 = dSP-b, 19 = dSP-C, 20 = dSP-_, 21 = d-LEV, 22 = LISt, 23 = r-1, 24 = r-2, 25 = r-3, 26 = r-4, 27 = r-34, 28 = r-234, 29 = r-ALL, 30 = Print |
| 40302 | | User Input 2 Action | 0 | 30 | 0 | Read/Write | See User Input 1 above |
| 40303 | | User F1 Key Action | 0 | 19 | 0 | Read/Write | 0 = NO, 1 = A-rEL, 2 = b-rEL, 3 = A-drL, 4 = b-drL, 5 = bAt, 6 = rtot, 7= r-HI, 8 = r-Lo, 9 = r-HL, 10 = d-LEV, 11 = LISt, 12 = r-1, 13 = r-2, 14 = r-3, 15 = r-4, 16 = r-34, 17 = r-234, 18 = r-ALL, 19 = Print |
| 40304 | | User F2 Key Action | 0 | 19 | 0 | Read/Write | See User F1 Key Description |
| 40305 | | User Reset Key Action | 0 | 19 | 0 | Read/Write | See User F1 Key Description |
| 40306 | | User F1 Second Action | 0 | 19 | 0 | Read/Write | See User F1 Key Description |
| 40307 | | User F2 Second Action | 0 | 19 | 0 | Read/Write | See User F1 Key Description |
| | | **DISPLAY/QUICK PRO MENU LOCKS** | | | | | **SEE MODULE 3 FOR DESCRIPTIONS OF PARAMETERS** |
| 40311 | | Input A Display Lock | 0 | 5 | 3 | Read/Write | 0=Loc, 1=Red, 2=Disp _, 3=Disp A, 4= Disp B, 5=Disp C |
| 40312 | | Input B Display | 0 | 5 | 4 | Read/Write | 0=Loc, 1=Red, 2=Disp _, 3=Disp A, 4= Disp B, 5=Disp C |
| 40313 | | Calculation Display | 0 | 5 | 5 | Read/Write | 0=Loc, 1=Red, 2=Disp _, 3=Disp A, 4= Disp B, 5=Disp C |
| 40314 | | Maximum (Hi) Value | 0 | 5 | 0 | Read/Write | 0=Loc, 1=Red, 2=Disp _, 3=Disp A, 4= Disp B, 5=Disp C |
| 40315 | | Minimum (Lo) Value | 0 | 5 | 0 | Read/Write | 0=Loc, 1=Red, 2=Disp _, 3=Disp A, 4= Disp B, 5=Disp C |
| 40316 | | Total Display | 0 | 5 | 0 | Read/Write | 0=Loc, 1=Red, 2=Disp _, 3=Disp A, 4= Disp B, 5=Disp C |
| 40317 | | SP1 Quick Pro | 0 | 2 | 0 | Read/Write | 0 = Lock, 1=Read, 2=Enter |
| 40318 | | SP2 Quick Pro | 0 | 2 | 0 | Read/Write | 0 = Lock, 1=Read, 2=Enter |
| 40319 | | SP3 Quick Pro | 0 | 2 | 0 | Read/Write | 0 = Lock, 1=Read, 2=Enter |
| 40320 | | SP4 Quick Pro | 0 | 2 | 0 | Read/Write | 0 = Lock, 1=Read, 2=Enter |
| 40321 | | Program Mode Security Code | 0 | 250 | 0 | Read/Write | |
| | | **SECONDARY PARAMETERS** | | | | | **SEE MODULE 4 FOR DESCRIPTIONS OF PARAMETERS** |
| 40029* | | Input A Offset Value (Hi word) | -19999 | 99999 | 0 | Read/Write | *Value shown here for reference |
| 40030* | | Input A Offset Value (Lo word) | | | | | |
| 40031* | | Input B Offset Value (Hi word) | -19999 | 99999 | 0 | Read/Write | *Value shown here for reference |
| 40032* | | Input B Offset Value (Lo word) | | | | | |

[1] For Input Registers, replace the 4xxxx with a 3xxxx in the above register address. The 3xxxx are a mirror of the 4xxxx Holding Registers.
[2] An attempt to exceed a limit will set the register to its high or low limit value.

| REGISTER ADDRESS [1] | REGISTER NAME | LOW LIMIT [2] | HIGH LIMIT [2] | FACTORY SETTING | ACCESS | COMMENTS |
|---|---|---|---|---|---|---|
| | **SECONDARY PARAMETERS (Continued)** | | | | | **SEE MODULE 4 FOR DESCRIPTIONS OF PARAMETERS** |
| 40331 | Max (Hi) Value Assignment | 0 | 4 | 0 | Read/Write | 0=A-Rel, 1=A-Abs, 2=b-Rel, 3=bAbs, 4=Calc |
| 40332 | Max (Hi) Capture Delay Time | 0 | 32750 | 10 | Read/Write | 0=Max Update Rate, 1=0.1 sec |
| 40333 | Min (Lo) Value Assignment | 0 | 4 | 0 | Read/Write | 0=A-Rel, 1=A-Abs, 2=b-Rel, 3=bAbs, 4=Calc |
| 40334 | Min (Lo) Capture Delay Time | 0 | 32750 | 10 | Read/Write | 0=Max Update Rate, 1=0.1 sec |
| 40335 | Display Update Time | 0 | 4 | 0 | Read/Write | 0=1 Rdg/sec, 1=2 Rdgs/sec, 2=5 Rdgs/sec, 3=10 Rdgs/sec, 4=20 Rdgs/sec |
| 40336 | Units Annunciator Backlight | 0 | 1 | 0 | Read/Write | 0=Off, 1=On |
| 40337 | Calculation Function | 0 | 5 | 0 | Read/Write | 0 = C+A+B 1 = C-A-B 2 = C+A-B<br>3 = A∗B/C 4 = C∗A/B 5 = C(A/B-1)<br>A=Input A, B=Input B, C=Calculation Constant |
| 40338 | Calculation Display Decimal Point | 0 | 4 | 3 | Read/Write | 0=0, 1=0.0, 2=0.00, 3=0.000, 4=0.0000 |
| 40339 | Calculation Constant Value High | -19999 | 99999 | 1000 | Read/Write | |
| 40340 | Calculation Constant Value Low | | | | | |
| 40341 | Calculation Display Rounding Factor | 0 | 6 | 0 | Read/Write | 0=1, 1=2, 2=5, 3=10, 4=20, 5=50, 6=100 |
| 40342 | Calculation Display Filter Value | 0 | 250 | 10 | Read/Write | 1=0.1 Second |
| 40343 | Calculation Filter Band | 0 | 250 | 10 | Read/Write | 1=1 display unit |
| | **TOTALIZER PARAMETERS** | | | | | |
| 40351 | Total Assignment | 0 | 2 | 0 | Read/Write | 0=A-Rel, 1= b-Rel, 2= Calc |
| 40352 | Total Decimal Point | 0 | 4 | 2 | Read/Write | 0=0, 1= 0.0, 2=0.00, 3=0.000, 4=0.0000 |
| 40353 | Total Timebase | 0 | 3 | 1 | Read/Write | 0=Second, 1=Minute, 2=Hour, 3=Day |
| 40354 | Total Scale Factor | 0 | 65000 | 1000 | Read/Write | 1=0.001 |
| 40355 | Total Low Cut Value (Hi word) | -19999 | 99999 | -19999 | Read/Write | |
| 40356 | Total Low Cut Value (Lo word) | -19999 | 99999 | -19999 | Read/Write | |
| 40357 | Total Reset at Power Up | 0 | 1 | 0 | Read/Write | 0 = No, 1 = Yes |
| | **SETPOINT 1 OUTPUT PARAMETERS**<br>Note: SP Values are located at Registers 40013-40021 | | | | | **SEE MODULE 6 FOR DESCRIPTION OF PARAMETERS (APPLIES ONLY IF SP OPTION CARD, PAXCDS, IS INSTALLED)** |
| 40361 | Assignment | 0 | 6 | 0 | Read/Write | 0=None 1=A-Rel 2=A-Abs 3=b-Rel<br>4=b-Abs 5=Calc 6=Tot |
| 40362 | Action | 0 | 10 | 0 | Read/Write | 0=No, 1=Ab-HI, 2=Ab-Lo, 3=AU-HI, 4=AU-LO, 9=totLo, 10=totHI; Do not use 5-8. |
| 40363 | Hysteresis | 1 | 65000 | 2 | Read/Write | 1=1 Display Unit |
| 40364 | On Delay | 0 | 32750 | 0 | Read/Write | 1=0.1 Second |
| 40365 | Off Delay | 0 | 32750 | 0 | Read/Write | 1=0.1 Second |
| 40366 | Output Logic | 0 | 1 | 0 | Read/Write | 0=Normal, 1=Reverse |
| 40367 | Reset | 0 | 2 | 0 | Read/Write | 0=Auto, 1=Latch1, 2=Latch2 |
| 40368 | Standby | 0 | 1 | 0 | Read/Write | 0=No, 1 = Yes |
| 40369 | Lit - Annunciator | 1 | 3 | 1 | Read/Write | 0=Off, 1=Normal, 2=Reverse, 3=Flash |
| | **SETPOINT 2 OUTPUT PARAMETERS** | | | | | |
| 40371 | Assignment | 0 | 6 | 0 | Read/Write | 0=None 1=A-Rel 2=A-Abs 3=b-Rel<br>4=b-Abs 5=Calc 6=Tot |
| 40372 | Action | 0 | 10 | 0 | Read/Write | 0=No, 1=Ab-HI, 2=Ab-Lo, 3=AU-HI, 4=AU-LO, 5=dE-HI, 6=dE-LO, 7=bANd, 8=bNdIn, 9=totLo, 10=totHI |
| 40373 | Hysteresis | 1 | 65000 | 2 | Read/Write | 1=1 Display Unit |
| 40374 | On Delay | 0 | 32750 | 0 | Read/Write | 1=0.1 Second |
| 40375 | Off Delay | 0 | 32750 | 0 | Read/Write | 1=0.1 Second |
| 40376 | Output Logic | 0 | 1 | 0 | Read/Write | 0=Normal, 1=Reverse |
| 40377 | Reset | 0 | 2 | 0 | Read/Write | 0=Auto, 1=Latch1, 2=Latch2 |
| 40378 | Standby | 0 | 1 | 0 | Read/Write | 0=No, 1 = Yes |
| 40379 | Lit - Annunciator | 0 | 3 | 1 | Read/Write | 0=Off, 1=Normal, 2=Reverse, 3=Flash |

[1] For Input Registers, replace the 4xxxx with a 3xxxx in the above register address. The 3xxxx are a mirror of the 4xxxx Holding Registers.
[2] An attempt to exceed a limit will set the register to its high or low limit value.

| REGISTER ADDRESS [1] | REGISTER NAME | LOW LIMIT [2] | HIGH LIMIT [2] | FACTORY SETTING | ACCESS | COMMENTS |
|---|---|---|---|---|---|---|
| | **SETPOINT 3 OUTPUT PARAMETERS** | | | | | |
| 40381 | Assignment | 0 | 6 | 0 | Read/Write | 0=None 1=A-Rel 2=A-Abs 3=b-Rel 4=bAbs 5=Calc 6=Tot |
| 40382 | Action | 0 | 10 | 0 | Read/Write | 0=No, 1=Ab-HI, 2=Ab-Lo, 3=AU-HI, 4=AU-LO, 9=totLo, 10=totHI; Do not use 5-8. |
| 40383 | Hysteresis | 1 | 65000 | 2 | Read/Write | 1=1 Display Unit |
| 40384 | On Delay | 0 | 32750 | 0 | Read/Write | 1=0.1 Second |
| 40385 | Off Delay | 0 | 32750 | 0 | Read/Write | 1=0.1 Second |
| 40386 | Output Logic | 0 | 1 | 0 | Read/Write | 0=Normal, 1=Reverse |
| 40387 | Reset | 0 | 2 | 0 | Read/Write | 0=Auto, 1=Latch1, 2=Latch2 |
| 40388 | Standby | 0 | 1 | 0 | Read/Write | 0=No, 1 = Yes |
| 40389 | Lit - Annunciator | 0 | 3 | 1 | Read/Write | 0=Off, 1=Normal, 2=Reverse, 3=Flash |
| | **SETPOINT 4 OUTPUT PARAMETERS** | | | | | |
| 40391 | Assignment | 0 | 6 | 0 | Read/Write | 0=None 1=A-Rel 2=A-Abs 3=b-Rel 4=bAbs 5=Calc 6=Tot |
| 40392 | Action | 0 | 10 | 0 | Read/Write | 0=No, 1=Ab-HI, 2=Ab-Lo, 3=AU-HI, 4=AU-LO, 5=dE-HI, 6=dE-LO, 7=bANd, 8=bNdIn, 9=totLo, 10=totHI |
| 40393 | Hysteresis | 1 | 65000 | 2 | Read/Write | 1=1 Display Unit |
| 40394 | On Delay | 0 | 32750 | 0 | Read/Write | 1=0.1 Second |
| 40395 | Off Delay | 0 | 32750 | 0 | Read/Write | 1=0.1 Second |
| 40396 | Output Logic | 0 | 1 | 0 | Read/Write | 0=Normal, 1=Reverse |
| 40397 | Reset | 0 | 2 | 0 | Read/Write | 0=Auto, 1=Latch1, 2=Latch2 |
| 40398 | Standby | 0 | 1 | 0 | Read/Write | 0=No, 1 = Yes |
| 40399 | Lit - Annunciator | 0 | 3 | 1 | Read/Write | 0=Off, 1=Normal, 2=Reverse, 3=Flash |
| | **SERIAL COMMUNICATIONS PARAMETERS** | | | | | **SEE MODULE 7 FOR DESCRIPTION OF PARAMETERS** |
| 40401 | Type | 0 | 2 | 2 | Read/Write | 0=RLC Protocol, 1=Modbus RTU, 2=Modbus ASCII |
| 40402 | Baud Rate | 0 | 7 | 7 | Read/Write | 0=300, 1=600, 2=1200, 3=2400, 4=4.8k, 5=9.6k, 6=19.2k, 7=38.4k |
| 40403 | Data Bits | 0 | 1 | 1 | Read/Write | 0=7 bits, 1=8 bits |
| 40404 | Parity | 0 | 2 | 0 | Read/Write | 0=None, 1=Even, 2=Odd |
| 40405 | Address | 0 | 99 | 247 | Read/Write | RLC Protocol: 0-99 |
| | | 1 | 247 | | | Modbus: 1-247 |
| 40406 | Transmit Delay | 0 | 250 | 10 | Read/Write | 1=0.001 Second |
| 40407 | Abbreviated Transmission (RLC only) | 0 | 1 | | Read/Write | 0=No, 1=Yes<br>Not used when communications type is Modbus |
| 40408 | Print Options | 0 | 63 | 0 | Read/Write | 0=No, 1=Yes<br>Not used when communications type is Modbus<br>Bit 0 - Print Input A Value<br>Bit 1 - Print Input B Value<br>Bit 2 - Print CALC Value<br>Bit 3 - Print Max & Min Values<br>Bit 4 - Print Total Value<br>Bit 5 - Print Setpoint Values |
| 40409 | Load Serial Settings | 0 | 1 | 0 | Read/Write | Changing 40401-40406 will not update the PAXDP until this register is written with a 1. After the write, the communicating device must be changed to the new PAXDP settings and the register returns to 0. |
| | **ANALOG OUTPUT PARAMETERS** | | | | | **SEE MODULE 8 FOR DESCRIPTION OF PARAMETERS (APPLIES ONLY WHEN LINEAR OUTPUT CARD, PAXCDL IS INSTALLED)** |
| 40411 | Type | 0 | 2 | 1 | Read/Write | 0 = 0-20 mA, 1 = 4-20 mA, 2 = 0-10 V |
| 40412 | Assignment | 0 | 8 | 0 | Read/Write | 0=NONE, 1=A-REL, 2=A-AbS, 3=b-rEL, 4=b-AbS, 5=CALC, 6=tot, 7=HI, 8=LO |
| 40413 | Analog Low Value (Hi word) | -19999 | 99999 | 0 | Read/Write | Display value that corresponds with 0 V, 0 mA or 4 mA output |
| 40414 | Analog Low Value (Lo word) | | | | | |
| 40415 | Analog High Value (Hi word) | -19999 | 99999 | 10000 | Read/Write | Display value that corresponds with 10 V or 20 mA output |
| 40416 | Analog High Value (Lo word) | | | | | |
| 40417 | Update Time | 0 | 100 | 0 | Read/Write | 0=Max update rate, 1=0.1 second |

[1] For Input Registers, replace the 4xxxx with a 3xxxx in the above register address. The 3xxxx are a mirror of the 4xxxx Holding Registers.
[2] An attempt to exceed a limit will set the register to its high or low limit value.

| REGISTER ADDRESS [1] | REGISTER NAME | LOW LIMIT [2] | HIGH LIMIT [2] | FACTORY SETTING | ACCESS | COMMENTS |
|---|---|---|---|---|---|---|
| | **FACTORY SERVICE** | | | | | |
| 40501 | Factory Service Register | N/A | N/A | N/A | Read/Write | Factory Use Only - Do Not Modify |
| 40502 | Factory Service Data Register | N/A | N/A | N/A | Read/Write | Factory Use Only - Do Not Modify |
| 40503 | Main Display Number | 0 | 3 | 1 | Read/Write | 0=Display_, 1=Display A, 2=Display B, 3=Display C |
| 40504 | Power Up Errors | N/A | N/A | N/A | Read Only | Bit Cleared = No Error, Bit Set = Error<br>Bit 0 = Input A Hardware Error (ErInA)<br>Bit 1 = Input B Hardware Error (ErInb)<br>Bit 2 = Key Stuck at power-up Error (ErKEY)<br>Bit 3 = Power Down Data Checksum Error (EEPdn)<br>Bit 4 = Parameter Checksum Error (EEPar)<br>Bit 5 = Calibration Data Checksum error (EECal)<br>Bit 6 = Linear Output Card Calibration Checksum Data Error (EELin) |
| 40505 | Input A/B Error | N/A | N/A | N/A | Read Only | Bit Cleared = No Error, Bit Set = Error<br>Bit 0 = Input A Display Underflow (<-19999)<br>Bit 1 = Input A Display Overflow (>99999)<br>Bit 2 = Input A Signal Underrange (<13 V or <-26 mA)<br>Bit 3 = Input A Signal Overrange (>13 V or >26 mA)<br>Bit 4 = Input A Display Underflow (<-19999)<br>Bit 5 = Input A Display Overflow (>99999)<br>Bit 6 = Input A Signal Underrange (<13 V or <-26 mA)<br>Bit 7 = Input A Signal Overrange (>13 V or >26 mA) |
| 40506 | Total & Calculation Error | N/A | N/A | N/A | Read Only | Bit 0 = Calculation Display Underflow (<-19999)<br>Bit 1 = Calculation Display Overflow (>99999)<br>Bit 4 = Total Value Display Underflow (<-99999900)<br>Bit 5 = Total Value Display Overflow (>999999000) |
| 41001-41010 | Slave ID | N/A | N/A | N/A | Read Only | RLC-PAXDP a b <0100h><20h><20h><10h><br>16 Scratch<br>32 Reads<br>32 Writes<br>Version Number<br>b = Linear Card “0”=None, “1”=Yes<br>a = SP Card, “0”-No SP, “2” or “4” SP<br>(a = “0”, “2”, “4” SP card installed; b = “0” or “1” Linear Card installed), 1.00 version (or higher)32 reads, 32 writes 16 scratch |
| 41101-41116 | GUID/Scratch | N/A | N/A | N/A | Read/Write | Reserved (may be used in future RLC software) |

[1] For Input Registers, replace the 4xxxx with a 3xxxx in the above register address. The 3xxxx are a mirror of the 4xxxx Holding Registers.
[2] An attempt to exceed a limit will set the register to its high or low limit value.

# SERIAL RLC PROTOCOL COMMUNICATIONS

RLC Communications requires the Serial Communications Type Parameter (tYPE) be set to rLC.

## SENDING SERIAL COMMANDS AND DATA

When sending commands to the meter, a string containing at least one command character must be constructed. A command string consists of a command character, a value identifier, numerical data (if writing data to the meter) followed by a the command terminator character * or $.

### Command Chart

| Command | Description | Notes |
|---|---|---|
| N | Node (Meter) Address Specifier | Address a specific meter. Must be followed by a one or two digit node address. Not required when address = 0. |
| T | Transmit Value (read) | Read a register from the meter. Must be followed by register ID character. |
| V | Value change (write) | Write to register of the meter. Must be followed by register ID character and numeric data. |
| R | Reset | Reset a register or output. Must be followed by register ID character |
| P | Block Print Request (read) | Initiates a block print output. Registers are defined in programming. |

### Command String Construction

The command string must be constructed in a specific sequence. The meter does not respond with an error message to invalid commands. The following procedure details construction of a command string:

1. The first characters consist of the Node Address Specifier (N) followed by a 1 or 2 character address number. The address number of the meter is programmable. If the node address is 0, this command and the node address itself may be omitted. This is the only command that may be used in conjunction with other commands.
2. After the address specifier, the next character is the command character.
3. The next character is the Register ID. This identifies the register that the command affects. The P command does not require a Register ID character. It prints according to the selections made in print options.
4. If constructing a value change command (writing data), the numeric data is sent next.
5. All command strings must be terminated with the string termination characters * or $. The meter does not begin processing the command string until this character is received. See Timing Diagram figure for differences between terminating characters.

## Register Identification Chart

| ID | VALUE DESCRIPTION | REGISTER NAME [1] | COMMAND SUPPORTED[2] |
|---|---|---|---|
| A | Input A Relative Value | INA | T, R (reset command zeros or tares input) |
| B | Input B Relative Value | INB | T, R (reset command zeros or tares input) |
| C | Calculation Value | CLC | T |
| D | Total | TOT | T, R (reset command zeros Total) |
| E | Min | MIN | T, R (reset command loads current reading) |
| F | Max | MAX | T, R (reset command loads current reading) |
| G | Input A Absolute (Gross) Value | ABA | T |
| H | Input B Absolute (Gross) Value | ABB | T |
| I | Input A Offset | OFA | T, V |
| J | Input B Offset | OFB | T, V |
| M | Setpoint 1 | SP1 | T, V, R (reset command resets setpoint output) |
| O | Setpoint 2 | SP2 | T, V, R (reset command resets setpoint output) |
| Q | Setpoint 3 | SP3 | T, V, R (reset command resets setpoint output) |
| S | Setpoint 4 | SP4 | T, V, R (reset command resets setpoint output) |
| U | Auto/Manual Register | MMR | T, V |
| W | Analog Output Register | AOR | T, V |
| X | Setpoint Register | SOR | T, V |

1. Register Names are also used as Register Mnemonics during full transmission.
2. The registers associated with the P command are set up in Print Options (Module 7). Unless otherwise specified, the Transmit Details apply to both T and V Commands.

## Command String Examples:

1. Address = 17, Write 350 to Setpoint 1
   String: N17VM350*
2. Address = 5, Read Input A value
   String: N5TA*
3. Address = 0, Reset Setpoint 4 output
   String: RS*

## Transmitting Data To the Meter

Numeric data sent to the meter must be limited to Transmit Details listed in the Register Identification Chart. Leading zeros are ignored. Negative numbers must have a minus sign. The meter ignores any decimal point and conforms the number to the scaled resolution. (ie. The meter's scaled decimal point position is set for 0.0 and 25 is written to a register. The value of the register is now 2.5. In this case, write a value of 250 to equal 25.0).

*Note: Since the meter does not issue a reply to value change commands, follow with a transmit value command for readback verification.*

## Transmitting Data From the Meter

Data is transmitted from the meter in response to either a transmit command (T), a print block command (P) or User Function print request. The response from the meter is either a full field transmission or an abbreviated transmission. See Abbreviated Printing (Abru) parameter.

## Full Transmission

| Byte | Description |
|---|---|
| 1, 2 | 2 byte Node (Meter) Address field [00-99] |
| 3 | <SP> (Space) |
| 4-6 | 3 byte Register Mnemonic field |
| 7-18 | 12 byte numeric data field: 10 bytes for number, one byte for sign, one byte for decimal point |
| 19 | <CR> (Carriage return) |
| 20 | <LF> (Line feed) |
| 21 | <SP> (Space)☆ |
| 22 | <CR> (Carriage return)☆ |
| 23 | <LF> (Line feed)☆ |

☆ *These characters only appear in the last line of a block print.*

The first two characters transmitted (bytes 1 and 2) are the unit address. If the address assigned is 00, two spaces are substituted. A space (byte 3) follows the unit address field. The next three characters (bytes 4 to 6) are the register mnemonic. The numeric data is transmitted next.

The numeric field (bytes 7 to 18) is 12 characters long. When the requested value exceeds eight digits for count values or five digits for rate values. Byte 8 is always a space. The remaining ten positions of this field (bytes 9 to 18) consist of a minus sign (for negative values), a floating decimal point (if applicable), and eight positions for the requested value. The data within bytes 9 to 18 is right-aligned with leading spaces for any unfilled positions.

The end of the response string is terminated with <CR> (byte 19), and <LF> (byte 20). When a block print is finished, an extra <SP> (byte 21), <CR> (byte 22), and <LF> (byte 23) are used to provide separation between the transmissions.

## Abbreviated Transmission

| Byte | Description |
|---|---|
| 1-12 | 12 byte data field, 10 bytes for number, one byte for sign, one byte for decimal point |
| 13 | <CR> (Carriage return) |
| 14 | <LF> (Line feed) |
| 15 | <SP> (Space)☆ |
| 16 | <CR> (Carriage return)☆ |
| 17 | <LF> (Line feed)☆ |

☆ *These characters only appear in the last line of a block print.*

The abbreviated response suppresses the address and register mnemonics, leaving only the numeric part of the response.

## Meter Response Examples:

1. Address = 17, full field response, Input A = 875
   17 INA 875 <CR><LF>
2. Address = 0, full field response, Setpoint 2 = -250.5
   SP2 -250.5<CR><LF>
3. Address = 0, abbreviated response, Setpoint 2 = 250, last line of block print
   250<CR><LF><SP><CR><LF>

### Auto/Manual Mode Register (MMR) ID: U

This register sets the controlling mode for the outputs. In Auto Mode (0) the meter controls the setpoint and analog output. In Manual Mode (1) the outputs are defined by the registers SOR and AOR. When transferring from auto mode to manual mode, the meter holds the last output value (until the register is changed by a write). Each output may be independently changed to auto or manual. In a write command string (VU), any character besides 0 or 1 in a field will not change the corresponding output mode.

U abcde
- e = Analog Output
- d = SP4
- c = SP3
- b = SP2
- a = SP1

**Example**: VU00011 places SP4 and Analog in manual.

### Analog Output Register (AOR) ID: W

This register stores the present signal value of the analog output. The range of values of this register is 0 to 4095, which corresponds to the analog output range per the following chart:

| Register Value | Output Signal* | | |
|---|---|---|---|
| | 0-20 mA | 4-20 mA | 0-10V |
| 0 | 0.000 | 4.000 | 0.000 |
| 1 | 0.005 | 4.004 | 0.0025 |
| 2047 | 10.000 | 12.000 | 5.000 |
| 4094 | 19.995 | 19.996 | 9.9975 |
| 4095 | 20.000 | 20.000 | 10.000 |

**Due to the absolute accuracy rating and resolution of the output card, the actual output signal may differ 0.15% FS from the table values. The output signal corresponds to the range selected (0-20 mA, 4-20 mA or 0-10 V).*

Writing to this register (VW) while the analog output is in the Manual Mode causes the output signal level to update immediately to the value sent. While in the Automatic Mode, this register may be written to, but it has no effect until the analog output is placed in the manual mode. When in the Automatic Mode, the meter controls the analog output signal level. Reading from this register (TW) will show the present value of the analog output signal.

**Example**: VW2047 will result in an output of 10.000 mA, 12.000 mA or 5.000V depending on the range selected.

### Setpoint Output Register (SOR) ID: X

This register stores the states of the setpoint outputs. Reading from this register (TX) will show the present state of all the setpoint outputs. A “0” in the setpoint location means the output is off and a “1” means the output is on.

X abcd
- d = SP4
- c = SP3
- b = SP2
- a = SP1

In Automatic Mode, the meter controls the setpoint output state. In Manual Mode, writing to this register (VX) will change the output state. Sending any character besides 0 or 1 in a field or if the corresponding output was not first in manual mode, the corresponding output value will not change. (It is not necessary to send least significant 0s.)

**Example**: VX10 will result in output 1 on and output 2 off.

## COMMAND RESPONSE TIME

The meter can only receive data or transmit data at any one time (half-duplex operation). When sending commands and data to the meter, a delay must be imposed before sending another command. This allows enough time for the meter to process the command and prepare for the next command.

At the start of the time interval t1, the computer program prints or writes the string to the com port, thus initiating a transmission. During t1, the command characters are under transmission and at the end of this period, the command terminating character (*) is received by the meter. The time duration of t1 is dependent on the number of characters and baud rate of the channel.

$$t1 = (10 * \#\ \text{of characters}) / \text{baud rate}$$

At the start of time interval t2, the meter starts the interpretation of the command and when complete, performs the command function. This time interval t2 varies from 2 msec to 15 msec. If no response from the meter is expected, the meter is ready to accept another command.

If the meter is to reply with data, the time interval t2 is controlled by the use of the command terminating character and the Serial Transmit Delay parameter (**dELAY**). The standard command line terminating character is '*'. This terminating character results in a response time window of the Serial Transmit Delay time (**dELAY**) plus 15msec. maximum. The **dELAY** parameter should be programmed to a value that allows sufficient time for the release of the sending driver on the RS485 bus. Terminating the command line with '$' results in a response time window (t2) of 2 msec minimum and 15 msec maximum. The response time of this terminating character requires that sending drivers release within 2 msec after the terminating character is received.

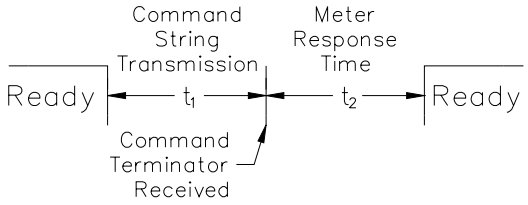
At the beginning of time interval t3, the meter responds with the first character of the reply. As with t1, the time duration of t3 is dependent on the number of characters and baud rate of the channel.

$$t3 = (10 * \#\ \text{of characters}) / \text{baud rate}.$$

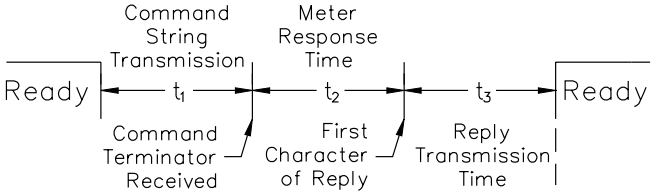
At the end of t3, the meter is ready to receive the next command. The maximum serial throughput of the meter is limited to the sum of the times t1, t2 and t3.

### *Timing Diagrams*

**NO REPLY FROM METER**




**RESPONSE FROM METER**



## COMMUNICATION FORMAT

Data is transferred from the meter through a serial communication channel. In serial communications, the voltage is switched between a high and low level at a predetermined rate (baud rate) using ASCII encoding. The receiving device reads the voltage levels at the same intervals and then translates the switched levels back to a character.

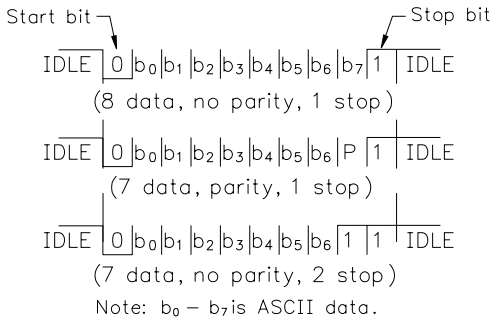
The voltage level conventions depend on the interface standard. The table lists the voltage levels for each standard.

| LOGIC | INTERFACE STATE | RS232* | RS485* |
|---|---|---|---|
| 1 | mark (idle) | TXD,RXD; -3 to -15 V | a-b < -200 mV |
| 0 | space (active) | TXD,RXD; +3 to +15 V | a-b > +200 mV |
| * Voltage levels at the Receiver | | | |

Data is transmitted one byte at a time with a variable idle period between characters (0 to ∞). Each ASCII character is "framed" with a beginning start bit, an optional parity bit and one or more ending stop bits. The data format and baud rate must match that of other equipment in order for communication to take place. The figures list the data formats employed by the meter.

### Start bit and Data bits

Data transmission always begins with the start bit. The start bit signals the receiving device to prepare for reception of data. One bit period later, the least significant bit of the ASCII encoded character is transmitted, followed by the remaining data bits. The receiving device then reads each bit position as they are transmitted.




**Character Frame Figure**

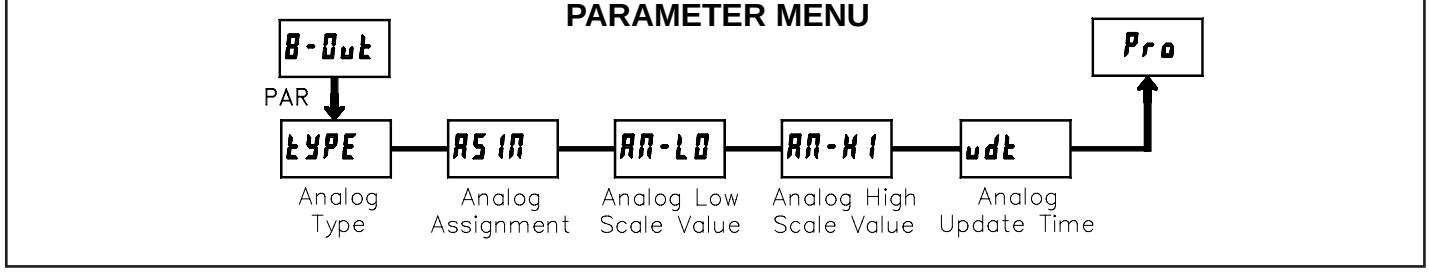
### Parity bit

After the data bits, the parity bit is sent. The transmitter sets the parity bit to a zero or a one, so that the total number of ones contained in the transmission (including the parity bit) is either even or odd. This bit is used by the receiver to detect errors that may occur to an odd number of bits in the transmission. However, a single parity bit cannot detect errors that may occur to an even number of bits. Given this limitation, the parity bit is often ignored by the receiving device. The PAX meter ignores the parity bit of incoming data and sets the parity bit to odd, even or none (mark parity) for outgoing data.

### Stop bit

The last character transmitted is the stop bit. The stop bit provides a single bit period pause to allow the receiver to prepare to re-synchronize to the start of a new transmission (start bit of next byte). The receiver then continuously looks for the occurrence of the start bit. If 7 data bits and no parity is selected, then 2 stop bits are sent from the PAXDP.

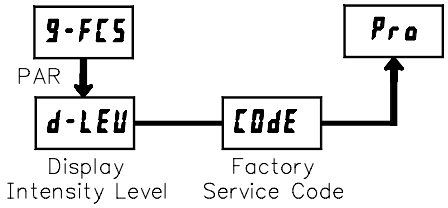
# 5.8 MODULE 8 - ANALOG OUTPUT PARAMETERS (8-Out)




| | | |
|---|---|---|
| tYPE - ANALOG TYPE | 0-20 | 0-10 |
| | 4-20 | |
| AS IN - ANALOG ASSIGNMENT | NONE | A-rEL |
| | A-Ab5 | b-rEL |
| | b-Ab5 | CALC |
| | tot | HI |
| | LO | |

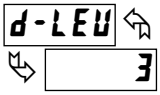
| | |
|---|---|
| AN-LO - ANALOG LOW SCALE VALUE | -19999 to 99999 |
| AN-HI - ANALOG HIGH SCALE VALUE | -19999 to 99999 |
| udt - ANALOG UPDATE TIME | 0.0 to 10.0 sec. |

# 5.9 MODULE 9 - FACTORY SERVICE OPERATIONS (9-FCS)



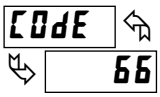

## PARAMETER MENU

### DISPLAY INTENSITY LEVEL



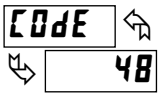

Enter the desired Display Intensity Level (0-15) by using the arrow keys. The display will actively dim or brighten as the levels are changed. This parameter also appears in Quick Programming Mode when enabled.

### RESTORE FACTORY DEFAULTS




Use the arrow keys to display **CodE 66** and press **PAR**. The meter will display **rESEt** and then return to **CodE 50**. Press **DSP** key to return to Display Mode. This will overwrite all user settings with the factory settings.

### CALIBRATION




The meter has been fully calibrated at the factory. Scaling to convert the input signal to a desired display value is performed in Module 1. If the meter appears to be indicating incorrectly or inaccurately, refer to Troubleshooting before attempting to calibrate the meter.

When recalibration is required (generally every 2 years), it should only be performed by qualified technicians using appropriate equipment. Calibration does not change any user programmed parameters. However, it may affect the accuracy of the input signal values previously stored using the Apply (**APLY**) Scaling Style.

Calibration may be aborted by disconnecting power to the meter before exiting Module 9. In this case, the existing calibration settings remain in effect.

### INPUT CALIBRATION

*WARNING: Calibration of this meter requires a signal source with an accuracy of 0.01% or better and an external meter with an accuracy of 0.005% or better.*

Before starting, verify that the Input Ranger Jumper is set for the range to be calibrated. Also verify that the precision signal source is connected and ready. Allow a 30 minute warm-up period before calibrating the meter. **NO** and **PAR** can be chosen to exit the calibration mode without any changes taking place. Then perform the following procedure:

1. Use the arrow keys to display (**CodE 48**) and press **PAR**.
2. Choose the input channel/range to be calibrated by using the arrow keys and press **PAR**. (**NO** and **PAR** can be chosen to exit the calibration mode without any changes taking place.)
3. When the zero range limit appears on the display, apply the appropriate:
   - Voltage range: dead short applied
   - Current range: open circuit
4. Press **PAR** and the top range limit will appear on the display after approximately 1 second.
5. With the top range limit on the display, apply the appropriate:
   - Voltage range: 10 VDC
   - Current range: 20 mADC
6. Press **PAR** and **CAL. NO** will appear on the display after approximately 1 second.
7. When **NO** appears, press **PAR** twice.
8. If the meter is not field scaled, then the input display should match the value of the input signal.
9. Repeat the above procedure for each input range to be calibrated.

### ANALOG OUTPUT CARD CALIBRATION

Before starting, verify that the precision voltmeter (voltage output) or current meter (current output) is connected and ready. Perform the following procedure:

1. Use the arrow keys to display **CodE 48** and press **PAR**.
2. Use the arrow keys to choose **OUt** and press **PAR**.
3. Using the chart below, step through the five selections to be calibrated. At each prompt, use the PAX arrow keys to adjust the external meter display to match the selection being calibrated. When the external reading matches, or if this range is not being calibrated, press **PAR**.

| SELECTION | EXTERNAL METER | ACTION |
|---|---|---|
| 0.0_A | 0.00 | Adjust if necessary, press **PAR** |
| 4.0_A | 4.00 | Adjust if necessary, press **PAR** |
| 20.0_A | 20.00 | Adjust if necessary, press **PAR** |
| 0.0u | 0.00 | Adjust if necessary, press **PAR** |
| 10.0u | 10.00 | Adjust if necessary, press **PAR** |

4. When **NO** appears remove the external meters and press **PAR** twice.

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# TROUBLESHOOTING

| PROBLEM | REMEDIES |
|---|---|
| NO DISPLAY | CHECK: Power level, power connections, Module 3 programming |
| PROGRAM LOCKED-OUT | CHECK: Active (lock-out) user input<br>ENTER: Security code requested |
| DISPLAY LOCKED-OUT | CHECK: Module 3 programming |
| INCORRECT INPUT DISPLAY VALUE | CHECK: Module 1 programming, Input Jumper position, input connections, input signal level, Module 4 Display Offset is zero, press DSP for Input Display<br>PERFORM: Module 9 Calibration (If the above does not correct the problem.) |
| "OLOL" in DISPLAY (SIGNAL HIGH) | CHECK: Module 1 programming, Input Range Jumper position, input connections, input signal level |
| "ULUL" in DISPLAY (SIGNAL LOW) | CHECK: Module 1 programming, Input Range Jumper position, input connections, input signal level |
| JITTERY DISPLAY | INCREASE: Module 1 filtering, rounding, input range<br>CHECK: Wiring is per EMC installation guidelines |
| MODULES or PARAMETERS NOT ACCESSIBLE | CHECK: Corresponding plug-in card installation |
| ERROR CODE (Err xxx or EE xxx) | PRESS: Reset KEY (If cannot clear contact factory.) |

For further assistance, contact technical support at the appropriate company numbers listed.

## PARAMETER VALUE CHART Programmer _____ Date _____

## PAXDP MODEL NUMBER _____ Meter# _____ Security Code _____

### 1- INP Signal Input Parameters

| DISPLAY | PARAMETER | FACTORY SETTING | INPUT A USER SETTING | INPUT B USER SETTING |
|---|---|---|---|---|
| rANGE | INPUT RANGE | VoLt | | |
| rAtE | UPDATE RANGE | 19.8 | | |
| dECPt | DISPLAY RESOLUTION | 0.000 | | |
| round | DISPLAY ROUNDING INCREMENT | 0.001 | | |
| FILtr | FILTER SETTING | 10 | | |
| bAnd | FILTER ENABLE BAND | 0.010 | | |
| Pts | SCALING POINTS | 2 | | |
| StyLE | SCALING STYLE | PEY | | |
| inP 1 | INPUT VALUE 1 | 0.000 | | |
| dSP 1 | DISPLAY VALUE 1 | 0.000 | | |
| inP 2 | INPUT VALUE 2 | 10.000 | | |
| dSP 2 | DISPLAY VALUE 2 | 10.000 | | |
| inP 3 | INPUT VALUE 3 | 0.000 | | |
| dSP 3 | DISPLAY VALUE 3 | 0.000 | | |
| inP 4 | INPUT VALUE 4 | 0.000 | | |
| dSP 4 | DISPLAY VALUE 4 | 0.000 | | |
| inP 5 | INPUT VALUE 5 | 0.000 | | |
| dSP 5 | DISPLAY VALUE 5 | 0.000 | | |
| inP 6 | INPUT VALUE 6 | 0.000 | | |
| dSP 6 | DISPLAY VALUE 6 | 0.000 | | |

| DISPLAY | PARAMETER | FACTORY SETTING | INPUT A USER SETTING | INPUT B USER SETTING |
|---|---|---|---|---|
| inP 7 | INPUT VALUE 7 | 0.000 | | |
| dSP 7 | DISPLAY VALUE 7 | 0.000 | | |
| inP 8 | INPUT VALUE 8 | 0.000 | | |
| dSP 8 | DISPLAY VALUE 8 | 0.000 | | |
| inP 9 | INPUT VALUE 9 | 0.000 | | |
| dSP 9 | DISPLAY VALUE 9 | 0.000 | | |
| inP 10 | INPUT VALUE 10 | 0.000 | | |
| dSP 10 | DISPLAY VALUE 10 | 0.000 | | |
| inP 11 | INPUT VALUE 11 | 0.000 | | |
| dSP 11 | DISPLAY VALUE 11 | 0.000 | | |
| inP 12 | INPUT VALUE 12 | 0.000 | | |
| dSP 12 | DISPLAY VALUE 12 | 0.000 | | |
| inP 13 | INPUT VALUE 13 | 0.000 | | |
| dSP 13 | DISPLAY VALUE 13 | 0.000 | | |
| inP 14 | INPUT VALUE 14 | 0.000 | | |
| dSP 14 | DISPLAY VALUE 14 | 0.000 | | |
| inP 15 | INPUT VALUE 15 | 0.000 | | |
| dSP 15 | DISPLAY VALUE 15 | 0.000 | | |
| inP 16 | INPUT VALUE 16 | 0.000 | | |
| dSP 16 | DISPLAY VALUE 16 | 0.000 | | |

## 2-FnC User Input and Function Key Parameters

| DISPLAY | PARAMETER | FACTORY SETTING | USER SETTING |
|---|---|---|---|
| USr-1 | USER INPUT 1 | no | |
| USr-2 | USER INPUT 2 | no | |
| F1 | FUNCTION KEY 1 | no | |
| F2 | FUNCTION KEY 2 | no | |
| rSt | RESET KEY | no | |
| Sc-F1 | 2nd FUNCTION KEY 1 | no | |
| Sc-F2 | 2nd FUNCTION KEY 2 | no | |

## 3-LOC Display and Program Lockout Parameters

| DISPLAY | PARAMETER | FACTORY SETTING | USER SETTING |
|---|---|---|---|
| InP A | INPUT A ASSIGNMENT | dSP-A | |
| InP b | INPUT B ASSIGNMENT | dSP-b | |
| CALC | CALCULATION ASSIGNMENT | dSP-C | |
| HI | MAX DISPLAY LOCKOUT | LOC | |
| LO | MIN DISPLAY LOCKOUT | LOC | |
| tOt | TOTAL DISPLAY LOCKOUT | LOC | |
| SP-1 | SETPOINT 1 ACCESS | LOC | |
| SP-2 | SETPOINT 2 ACCESS | LOC | |
| SP-3 | SETPOINT 3 ACCESS | LOC | |
| SP-4 | SETPOINT 4 ACCESS | LOC | |
| CodE | SECURITY CODE | 0 | |

## 4-SEC Secondary Function Parameters

| DISPLAY | PARAMETER | FACTORY SETTING | USER SETTING |
|---|---|---|---|
| OFS-A | INPUT A OFFSET VALUE | 0.000 | |
| OFS-b | INPUT B OFFSET VALUE | 0.000 | |
| HI-AS | MAX CAPTURE ASSIGNMENT | A-rEL | |
| HI-t | MAX CAPTURE DELAY TIME | 1.0 | |
| LO-AS | MIN CAPTURE ASSIGNMENT | A-rEL | |
| LO-t | MIN CAPTURE DELAY TIME | 1.0 | |
| dSP-t | DISPLAY UPDATE TIME | 1 | |
| b-LIt | UNITS LABEL BACKLIGHT | OFF | |
| CFunc | CALCULATION FUNCTION | c+A+b | |
| C dP | CALCULATION DECIMAL POINT | 0.000 | |
| conSt | CALCULATION CONSTANT VALUE | 1.000 | |
| C rnd | CALCULATION ROUNDING | 0.001 | |
| C FLt | CALCULATION FILTER SETTING | 1.0 | |
| C bnd | CALCULATION FILTER BAND | 0.010 | |

## 5-tOt Totalizer (Integrator) Parameters

| DISPLAY | PARAMETER | FACTORY SETTING | USER SETTING |
|---|---|---|---|
| AS In | TOTALIZER ASSIGNMENT | A-rEL | |
| dECPt | TOTALIZER DECIMAL POINT | 0.000 | |
| tbASE | TOTALIZER TIME BASE | Min | |
| SCFAC | TOTALIZER SCALE FACTOR | 1.000 | |
| Locut | TOTALIZER LOW CUT VALUE | -19.999 | |
| P-uP | TOTALIZER POWER-UP RESET | no | |

## 7-SrL Serial Communication Parameters

| DISPLAY | PARAMETER | FACTORY SETTING | USER SETTING |
|---|---|---|---|
| tYPE | COMMUNICATIONS TYPE | MbAS | |
| bAUd | BAUD RATE | 38400 | |
| dAtA | DATA BIT | 8 | |
| PAr | PARITY BIT | no | |
| Addr | METER ADDRESS | 247 | |
| dELAY | TRANSMIT DELAY | 0.010 | |
| Abru | ABBREVIATED PRINTING | no | |
| OPt | PRINT OPTIONS | no | |
| InP A | INPUT A VALUE | no | |
| InP b | INPUT B VALUE | no | |
| CALC | CALCULATION | no | |
| tot | PRINT TOTAL VALUE | no | |
| HILO | PRINT MAX & MIN VALUES | no | |
| SPnt | PRINT SETPOINT VALUES | no | |

Shaded area available when communications type is rLC.

## 8-Out Analog Output Parameters

| DISPLAY | PARAMETER | FACTORY SETTING | USER SETTING |
|---|---|---|---|
| tYPE | ANALOG TYPE | 4-20 | |
| AS In | ANALOG ASSIGNMENT | 0 | |
| An-LO | ANALOG LOW SCALE VALUE | 0 | |
| An-HI | ANALOG HIGH SCALE VALUE | 10000 | |
| udt | ANALOG UPDATE TIME | 0.0 | |

## 9-FCS Factory Setting Parameters

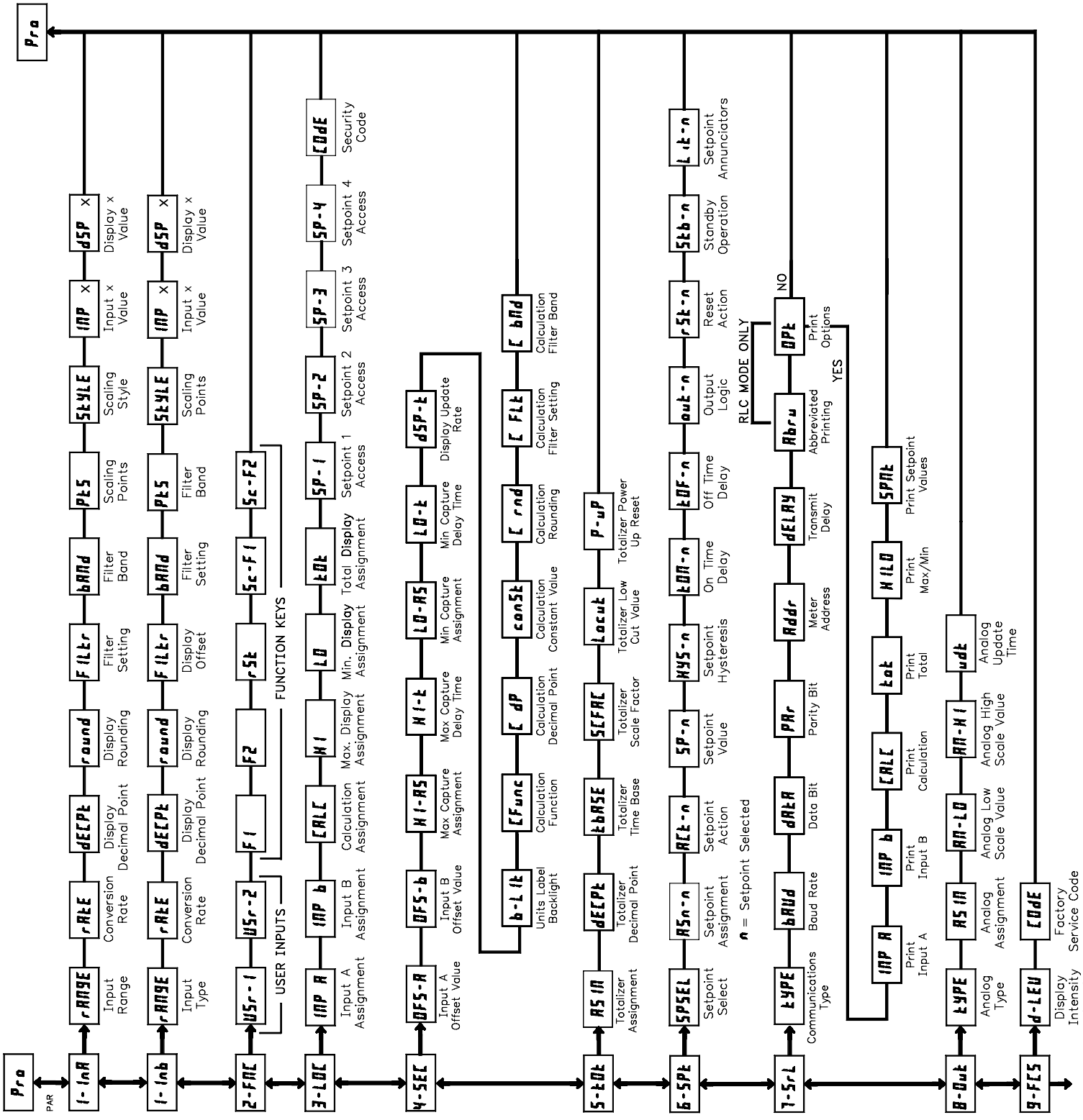
| DISPLAY | PARAMETER | FACTORY SETTING | USER SETTING |
|---|---|---|---|
| d-LEV | DISPLAY INTENSITY LEVEL | 3 | |

## 6-SPt Setpoint (Alarm) Parameters

| DISPLAY | PARAMETER | SP-1 FACTORY SETTING | SP-1 USER SETTING | SP-2 FACTORY SETTING | SP-2 USER SETTING | SP-3 FACTORY SETTING | SP-3 USER SETTING | SP-4 FACTORY SETTING | SP-4 USER SETTING |
|---|---|---|---|---|---|---|---|---|---|
| SPSEL | SELECT SETPOINT | no | | no | | no | | no | |
| ASn-n | SETPOINT ASSIGNMENT | none | | none | | none | | none | |
| ACt-n | SETPOINT ACTION | no | | no | | no | | no | |
| SP-n | SETPOINT VALUE (main) | 100 | | 200 | | 300 | | 400 | |
| | SETPOINT VALUE (alternate) * | 100 | | 200 | | 300 | | 400 | |
| HYS-n | SETPOINT HYSTERESIS | 2 | | 2 | | 2 | | 2 | |
| tOn-n | ON TIME DELAY | 0.0 | | 0.0 | | 0.0 | | 0.0 | |
| tOF-n | OFF TIME DELAY | 0.0 | | 0.0 | | 0.0 | | 0.0 | |
| out-n | OUTPUT LOGIC | nor | | nor | | nor | | nor | |
| rSt-n | RESET ACTION | AUto | | AUto | | AUto | | AUto | |
| Stb-n | STANDBY OPERATION | no | | no | | no | | no | |
| Lit-n | SETPOINT ANNUNCIATORS | nor | | nor | | nor | | nor | |

*Select alternate list to program these values.

# PAXDP PROGRAMMING QUICK OVERVIEW



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